

# Metric-affine gravity and Black holes

Sebastián Bahamonde

Postdoctoral Researcher at Tokyo Institute of Technology, Japan

Recent Research in Gravity, Zhejiang Normal University, 29/Nov/2022

Based on on JCAP **09** (2020), 057, Eur.Phys.J.C **81** (2021) 6, 495;

JCAP **01** (2022) no.01, 011; JCAP **04** (2022) no.04, 011; and 2210.05998

Jointly with Jorge Gigante Valcarcel.



東京工業大学

Tokyo Institute of Technology

# Overview of the Talk

## 1 Introduction to Metric-affine gravity

- Why modified gravity?
- Basic geometrical quantities

## 2 Metric-Affine gravity

- Curvature, torsion and nonmetricity
- Dynamics

## 3 MAG models with dynamical torsion and nonmetricity

- Weyl part of nonmetricity
- Axial symmetry in Weyl-Cartan geometry
- Spherical symmetry with Shears and Weyl (complete nonmetricity)

# General Relativity - Assumptions

General Relativity is based upon different assumptions that can be understood as the fulfilling of the Lovelock's theorem. Some assumptions are:

- **Equivalence principle**

# General Relativity - Assumptions

General Relativity is based upon different assumptions that can be understood as the fulfilling of the Lovelock's theorem. Some assumptions are:

- **Equivalence principle**
- **General covariance:** Invariant under diffeomorphisms and Local Lorentz transformations.

# General Relativity - Assumptions

General Relativity is based upon different assumptions that can be understood as the fulfilling of the Lovelock's theorem. Some assumptions are:

- **Equivalence principle**
- **General covariance:** Invariant under diffeomorphisms and Local Lorentz transformations.
- **Riemannian geometry:** The connection is the Levi-Civita one.

# General Relativity - Assumptions

General Relativity is based upon different assumptions that can be understood as the fulfilling of the Lovelock's theorem. Some assumptions are:

- **Equivalence principle**
- **General covariance:** Invariant under diffeomorphisms and Local Lorentz transformations.
- **Riemannian geometry:** The connection is the Levi-Civita one.
- **4-dimension**

# General Relativity - Assumptions

General Relativity is based upon different assumptions that can be understood as the fulfilling of the Lovelock's theorem. Some assumptions are:

- **Equivalence principle**
- **General covariance:** Invariant under diffeomorphisms and Local Lorentz transformations.
- **Riemannian geometry:** The connection is the Levi-Civita one.
- **4-dimension**
- **2nd order derivatives:** gravitational action contains only second derivatives.

# General Relativity - Assumptions

General Relativity is based upon different assumptions that can be understood as the fulfilling of the Lovelock's theorem. Some assumptions are:

- **Equivalence principle**
- **General covariance:** Invariant under diffeomorphisms and Local Lorentz transformations.
- **Riemannian geometry:** The connection is the Levi-Civita one.
- **4-dimension**
- **2nd order derivatives:** gravitational action contains only second derivatives.
- **Locality**



# Why modified gravity?

- GR is not compatible with quantum field theory;

# Why modified gravity?

- GR is not compatible with quantum field theory;
- The cosmological constant  $\Lambda$  problem; Dark energy, dark matter.

# Why modified gravity?

- GR is not compatible with quantum field theory;
- The cosmological constant  $\Lambda$  problem; Dark energy, dark matter.
- **The  $H_0$  tension:**  $5\sigma$  tension between current expansion rate  $H_0$  using Planck data and direct model-independent measurements in the local universe;

# Why modified gravity?

- GR is not compatible with quantum field theory;
- The cosmological constant  $\Lambda$  problem; Dark energy, dark matter.
- **The  $H_0$  tension:**  $5\sigma$  tension between current expansion rate  $H_0$  using Planck data and direct model-independent measurements in the local universe;
- Big Bang singularity;

# Why modified gravity?

- GR is not compatible with quantum field theory;
- The cosmological constant  $\Lambda$  problem; Dark energy, dark matter.
- **The  $H_0$  tension:**  $5\sigma$  tension between current expansion rate  $H_0$  using Planck data and direct model-independent measurements in the local universe;
- Big Bang singularity;
- What is really the inflaton?

# Why modified gravity?

- GR is not compatible with quantum field theory;
- The cosmological constant  $\Lambda$  problem; Dark energy, dark matter.
- **The  $H_0$  tension:**  $5\sigma$  tension between current expansion rate  $H_0$  using Planck data and direct model-independent measurements in the local universe;
- Big Bang singularity;
- What is really the inflaton?
- Strong gravity regime needs to be tested;

# Why modified gravity?

- GR is not compatible with quantum field theory;
- The cosmological constant  $\Lambda$  problem; Dark energy, dark matter.
- **The  $H_0$  tension:**  $5\sigma$  tension between current expansion rate  $H_0$  using Planck data and direct model-independent measurements in the local universe;
- Big Bang singularity;
- What is really the inflaton?
- Strong gravity regime needs to be tested;
- A good way to understand GR is to modify it;

# How to modify it?

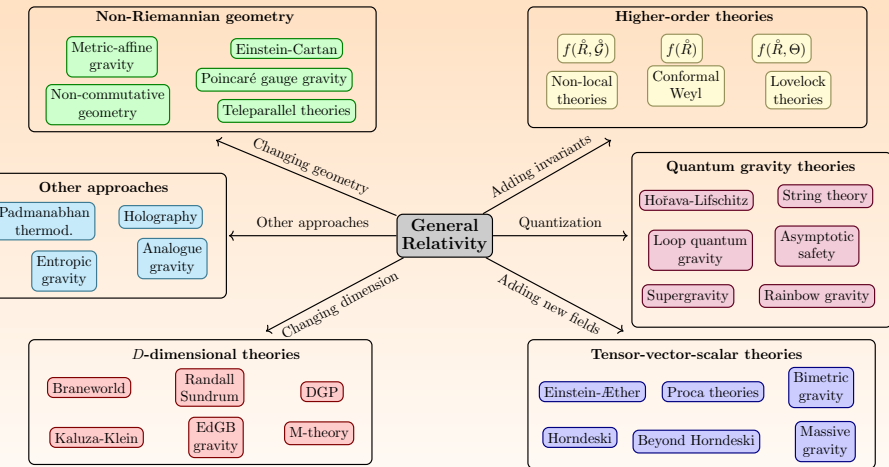


Figure: Classification of theories of gravity. (S. Bahamonde et al., "Teleparallel Gravity: From Theory to Cosmology," [arXiv:2106.13793 [gr-qc]].)



# Fundamental variables and characteristic tensors

- In the most general metric-affine setting, the fundamental variables are a **metric**  $g_{\mu\nu}$  (10 comp.) as well as the coefficients  $\tilde{\Gamma}^{\rho}_{\mu\nu}$  (64 comp.) of an **affine connection**.

# Fundamental variables and characteristic tensors

- In the most general metric-affine setting, the fundamental variables are a **metric**  $g_{\mu\nu}$  (10 comp.) as well as the coefficients  $\tilde{\Gamma}^{\rho}_{\mu\nu}$  (64 comp.) of an **affine connection**.
- The most general connection can be written as

# Fundamental variables and characteristic tensors

- In the most general metric-affine setting, the fundamental variables are a **metric**  $g_{\mu\nu}$  (10 comp.) as well as the coefficients  $\tilde{\Gamma}^\rho{}_{\mu\nu}$  (64 comp.) of an **affine connection**.
- The most general connection can be written as

## Connection decomposition

$$\tilde{\Gamma}^\lambda{}_{\mu\nu} = \overbrace{\Gamma^\lambda{}_{\mu\nu}}^{\text{Levi-Civita}}$$

# Fundamental variables and characteristic tensors

- In the most general metric-affine setting, the fundamental variables are a **metric**  $g_{\mu\nu}$  (10 comp.) as well as the coefficients  $\tilde{\Gamma}^\rho{}_{\mu\nu}$  (64 comp.) of an **affine connection**.
- The most general connection can be written as

## Connection decomposition

$$\tilde{\Gamma}^\lambda{}_{\mu\nu} = \overbrace{\Gamma^\lambda{}_{\mu\nu}}^{\text{Levi-Civita}}$$

# Fundamental variables and characteristic tensors

- In the most general metric-affine setting, the fundamental variables are a **metric**  $g_{\mu\nu}$  (10 comp.) as well as the coefficients  $\tilde{\Gamma}^\rho{}_{\mu\nu}$  (64 comp.) of an **affine connection**.
- The most general connection can be written as

## Connection decomposition

$$\tilde{\Gamma}^\lambda{}_{\mu\nu} = \overbrace{\Gamma^\lambda{}_{\mu\nu}}^{\text{Levi-Civita}} + \overbrace{\frac{1}{2} T^\lambda{}_{\mu\nu} - T_{(\mu}{}^\lambda{}_{\nu)}}^{\text{Torsion part}}$$

# Fundamental variables and characteristic tensors

- In the most general metric-affine setting, the fundamental variables are a **metric**  $g_{\mu\nu}$  (10 comp.) as well as the coefficients  $\tilde{\Gamma}^\rho{}_{\mu\nu}$  (64 comp.) of an **affine connection**.
- The most general connection can be written as

## Connection decomposition

$$\tilde{\Gamma}^\lambda{}_{\mu\nu} = \overbrace{\Gamma^\lambda{}_{\mu\nu}}^{\text{Levi-Civita}} + \overbrace{\frac{1}{2} T^\lambda{}_{\mu\nu} - T_{(\mu}{}^\lambda{}_{\nu)}}^{\text{Torsion part}} + \overbrace{\frac{1}{2} Q^\lambda{}_{\mu\nu} - Q_{(\mu}{}^\lambda{}_{\nu)}}^{\text{Nonmetricity part}},$$

# Fundamental variables and characteristic tensors

- In the most general metric-affine setting, the fundamental variables are a **metric**  $g_{\mu\nu}$  (10 comp.) as well as the coefficients  $\tilde{\Gamma}^\rho{}_{\mu\nu}$  (64 comp.) of an **affine connection**.
- The most general connection can be written as

## Connection decomposition

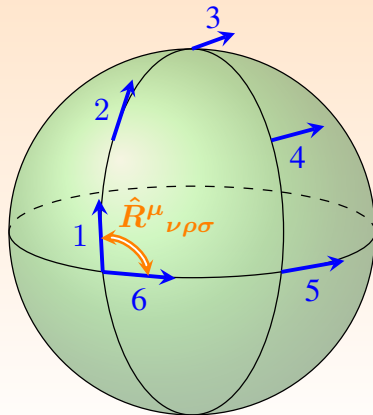
$$\tilde{\Gamma}^\lambda{}_{\mu\nu} = \underbrace{\Gamma^\lambda{}_{\mu\nu}}_{\text{Levi-Civita}} + \underbrace{\frac{1}{2} T^\lambda{}_{\mu\nu} - T_{(\mu}{}^\lambda{}_{\nu)}}_{\text{Torsion part}} + \underbrace{\frac{1}{2} Q^\lambda{}_{\mu\nu} - Q_{(\mu}{}^\lambda{}_{\nu)}}_{\text{Nonmetricity part}},$$

<b>Curvature</b>	$\tilde{R}^\mu{}_{\nu\rho\sigma} = \partial_\rho \tilde{\Gamma}^\mu{}_{\nu\sigma} - \partial_\sigma \tilde{\Gamma}^\mu{}_{\nu\rho} + \tilde{\Gamma}^\mu{}_{\tau\rho} \tilde{\Gamma}^\tau{}_{\nu\sigma} - \tilde{\Gamma}^\mu{}_{\tau\sigma} \tilde{\Gamma}^\tau{}_{\nu\rho}$
<b>Torsion</b>	$\tilde{T}^\mu{}_{\nu\rho} = \tilde{\Gamma}^\mu{}_{\rho\nu} - \tilde{\Gamma}^\mu{}_{\nu\rho}$
<b>Nonmetricity</b>	$\tilde{Q}_{\mu\nu\rho} = \tilde{\nabla}_\mu g_{\nu\rho} = \partial_\mu g_{\nu\rho} - \tilde{\Gamma}^\sigma{}_{\nu\mu} g_{\sigma\rho} - \tilde{\Gamma}^\sigma{}_{\rho\mu} g_{\nu\sigma}$

# What does curvature geometrically represent?

## Curvature tensor $\tilde{R}^\alpha_{\beta\mu\nu}$

Rotation experienced by a vector when it is parallel transported along a closed curve

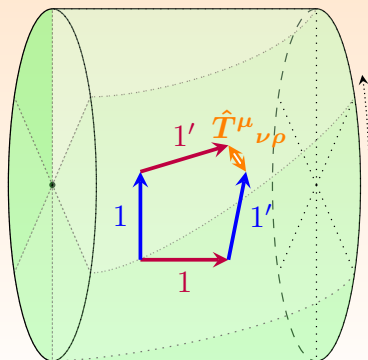




# What does torsion geometrically represent?

**Torsion tensor**  $\tilde{T}^{\alpha}_{\mu\nu}$

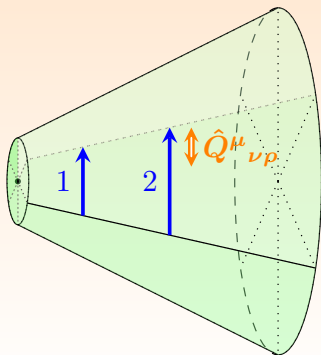
non-closure of the parallelogram formed when two infinitesimal vectors are parallel transported along each other.



# What does non-metricity geometrically represent?

## Non-metricity tensor $\tilde{Q}_{\alpha\mu\nu}$

measures how much the length and angle of vectors change as we parallel transport them, so in metric spaces the length of vectors is conserve



- **Riemann-Cartan geometry** ( $\tilde{Q}_{\alpha\mu\nu} = 0$ ): If non-metricity vanishes, the metric satisfies the metric-compatibility condition  $\tilde{\nabla}_{\mu}g_{\alpha\beta} = 0$ . Poincaré gravity assumes this geometry.

- **Riemann-Cartan geometry** ( $\tilde{Q}_{\alpha\mu\nu} = 0$ ): If non-metricity vanishes, the metric satisfies the metric-compatibility condition  $\tilde{\nabla}_{\mu}g_{\alpha\beta} = 0$ . Poincaré gravity assumes this geometry.
- **Weyl gravity** ( $\tilde{T}^{\alpha}_{\mu\nu} = 0$ ): If the torsion vanishes, the connection is called symmetric  $\tilde{\Gamma}^{\rho}_{[\mu\nu]} = 0$ .

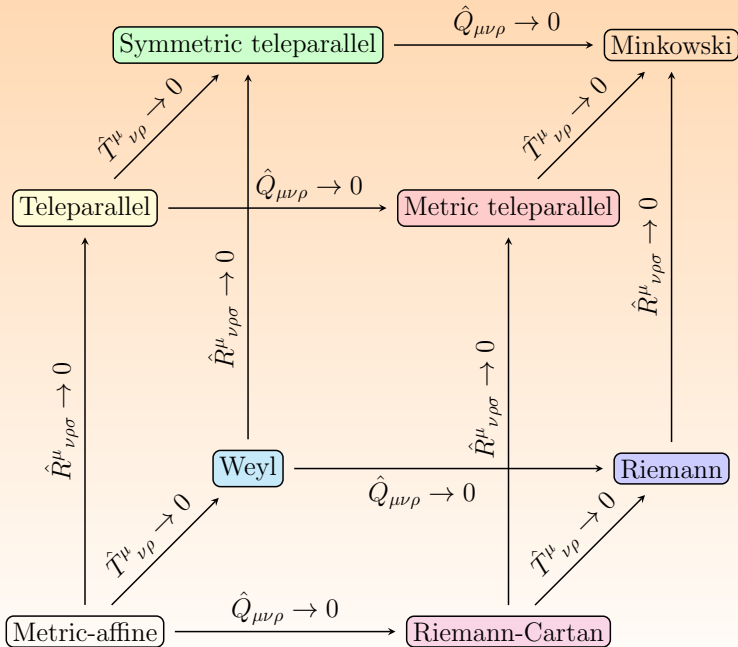
- **Riemann-Cartan geometry** ( $\tilde{Q}_{\alpha\mu\nu} = 0$ ): If non-metricity vanishes, the metric satisfies the metric-compatibility condition  $\tilde{\nabla}_{\mu}g_{\alpha\beta} = 0$ . Poincaré gravity assumes this geometry.
- **Weyl gravity** ( $\tilde{T}^{\alpha}_{\mu\nu} = 0$ ): If the torsion vanishes, the connection is called symmetric  $\tilde{\Gamma}^{\rho}_{[\mu\nu]} = 0$ .
- **General Teleparallel geometry** ( $\tilde{R}_{\alpha\mu\nu\beta} = 0$ ): In the case of vanishing curvature, the connection is flat.

- **Riemannian geometry** ( $\tilde{T}^\alpha{}_{\mu\nu} = 0, \tilde{Q}_{\alpha\mu\nu} = 0$ ): The connection is symmetric and metric compatible, leading to  $\tilde{\Gamma}^\rho{}_{\mu\nu} = \overset{\circ}{\Gamma}^\rho{}_{\mu\nu}$ . GR and the majority of the theories are here.

- **Riemannian geometry** ( $\tilde{T}^\alpha{}_{\mu\nu} = 0, \tilde{Q}_{\alpha\mu\nu} = 0$ ): The connection is symmetric and metric compatible, leading to  $\tilde{\Gamma}^\rho{}_{\mu\nu} = \overset{\circ}{\Gamma}^\rho{}_{\mu\nu}$ . GR and the majority of the theories are here.
- **Torsional Teleparallel geometry** ( $\tilde{R}_{\alpha\mu\nu\beta} = 0, \tilde{Q}_{\alpha\mu\nu} = 0$ ): The metric satisfies the metric-compatibility condition but torsion is non-zero. This talk will be based on this.

- **Riemannian geometry** ( $\tilde{T}^\alpha{}_{\mu\nu} = 0, \tilde{Q}_{\alpha\mu\nu} = 0$ ): The connection is symmetric and metric compatible, leading to  $\tilde{\Gamma}^\rho{}_{\mu\nu} = \overset{\circ}{\Gamma}^\rho{}_{\mu\nu}$ . GR and the majority of the theories are here.
- **Torsional Teleparallel geometry** ( $\tilde{R}_{\alpha\mu\nu\beta} = 0, \tilde{Q}_{\alpha\mu\nu} = 0$ ): The metric satisfies the metric-compatibility condition but torsion is non-zero. This talk will be based on this.
- **Symmetric Teleparallel geometry** ( $\tilde{R}_{\alpha\mu\nu\beta} = 0, \tilde{T}^\alpha{}_{\mu\nu} = 0$ ): Both torsion tensor and curvature are zero and the gravitational interactions are only mediated through non-metricity.





**Figure:** Classification of metric-affine geometries - Cube

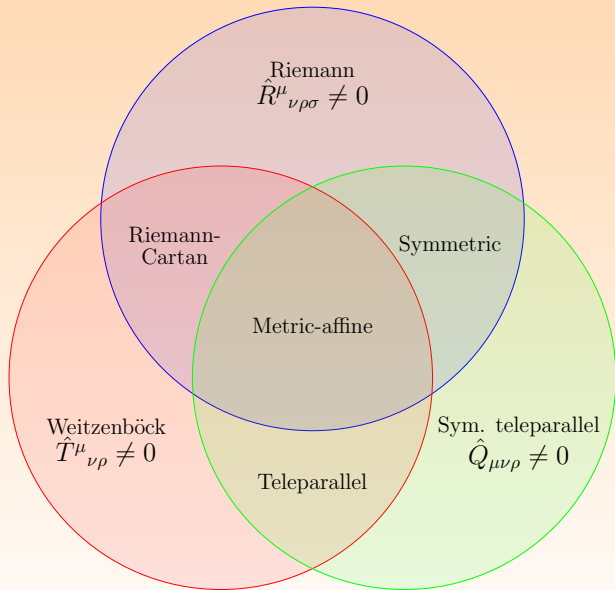


Figure: Classification of metric-affine geometries

# Overview of the Talk

- 1 Introduction to Metric-affine gravity
  - Why modified gravity?
  - Basic geometrical quantities
- 2 Metric-Affine gravity
  - Curvature, torsion and nonmetricity
  - Dynamics
- 3 MAG models with dynamical torsion and nonmetricity
  - Weyl part of nonmetricity
  - Axial symmetry in Weyl-Cartan geometry
  - Spherical symmetry with Shears and Weyl (complete nonmetricity)

- The curvature tensor of an affinely connected metric space-time contains corrections provided by the presence of torsion and nonmetricity: ( $\nabla_\nu$  just Levi-Civita)

$$\tilde{R}^\lambda{}_{\rho\mu\nu} = R^\lambda{}_{\rho\mu\nu} + \nabla_\mu N^\lambda{}_{\rho\nu} - \nabla_\nu N^\lambda{}_{\rho\mu} + N^\lambda{}_{\sigma\mu} N^\sigma{}_{\rho\nu} - N^\lambda{}_{\sigma\nu} N^\sigma{}_{\rho\mu},$$

where

$$N^\lambda{}_{\mu\nu} = \frac{1}{2} \left( T^\lambda{}_{\mu\nu} - T_\mu{}^\lambda{}_\nu - T_\nu{}^\lambda{}_\mu \right) + \frac{1}{2} \left( Q^\lambda{}_{\mu\nu} - Q_\mu{}^\lambda{}_\nu - Q_\nu{}^\lambda{}_\mu \right),$$

- The curvature tensor of an affinely connected metric space-time contains corrections provided by the presence of torsion and nonmetricity: ( $\nabla_\nu$  just Levi-Civita)

$$\tilde{R}^\lambda{}_{\rho\mu\nu} = R^\lambda{}_{\rho\mu\nu} + \nabla_\mu N^\lambda{}_{\rho\nu} - \nabla_\nu N^\lambda{}_{\rho\mu} + N^\lambda{}_{\sigma\mu} N^\sigma{}_{\rho\nu} - N^\lambda{}_{\sigma\nu} N^\sigma{}_{\rho\mu},$$

where

$$N^\lambda{}_{\mu\nu} = \frac{1}{2} \left( T^\lambda{}_{\mu\nu} - T_\mu{}^\lambda{}_\nu - T_\nu{}^\lambda{}_\mu \right) + \frac{1}{2} \left( Q^\lambda{}_{\mu\nu} - Q_\mu{}^\lambda{}_\nu - Q_\nu{}^\lambda{}_\mu \right),$$

- Furthermore, the latter also leads to the definition of three independent traces of this tensor, namely the Ricci and co-Ricci tensors:

$$\tilde{R}_{\mu\nu} = \tilde{R}^\lambda{}_{\mu\lambda\nu}, \quad \hat{R}_{\mu\nu} = \tilde{R}_\mu{}^\lambda{}_{\nu\lambda},$$

as well as the so-called homothetic curvature tensor  $\tilde{R}^\lambda{}_{\lambda\mu\nu}$ , which encodes the change of lengths of vectors provided by the trace part of nonmetricity under their parallel transport along closed loops.

- Due to torsion, this connection introduces modifications in the covariant derivative which indeed involves a change on its commutation relations when considering an arbitrary vector  $v^\lambda$ :

$$[\tilde{\nabla}_\mu, \tilde{\nabla}_\nu] v^\lambda = \tilde{R}^\lambda{}_{\rho\mu\nu} v^\rho + T^\rho{}_{\mu\nu} \tilde{\nabla}_\rho v^\lambda.$$

- Due to torsion, this connection introduces modifications in the covariant derivative which indeed involves a change on its commutation relations when considering an arbitrary vector  $v^\lambda$ :

$$[\tilde{\nabla}_\mu, \tilde{\nabla}_\nu] v^\lambda = \tilde{R}^\lambda{}_{\rho\mu\nu} v^\rho + T^\rho{}_{\mu\nu} \tilde{\nabla}_\rho v^\lambda.$$

- The change of lengths of a given vector  $k^\mu$  as well as the change of angles between two unit timelike vectors  $\hat{m}^\mu$  and  $\hat{n}^\mu$ , under a general parallel transport defined by a tangent vector  $V^\mu$ , is proportional to the nonmetricity tensor:

$$V^\lambda \tilde{\nabla}_\lambda ||\mathbf{k}||^2 = V^\lambda Q_{\lambda\mu\nu} k^\mu k^\nu,$$

$$V^\lambda \tilde{\nabla}_\lambda (g_{\mu\nu} \hat{m}^\mu \hat{n}^\nu) = V^\lambda Q_{\lambda\mu\nu} \hat{m}^\mu \hat{n}^\nu - \frac{1}{2} V^\lambda Q_{\lambda\mu\nu} (\hat{m}^\mu \hat{m}^\nu + \hat{n}^\mu \hat{n}^\nu) \hat{m}^\rho \hat{n}_\rho.$$

- Gravitational action with dynamical torsion and nonmetricity:

$$S = \int d^4x \sqrt{-g} \left[ \mathcal{L}_m - \frac{1}{16\pi} \mathcal{L}_g(\tilde{\mathcal{R}}, \mathcal{T}, \mathcal{Q}) \right].$$



# Dynamics of metric-affine geometry

- Gravitational action with dynamical torsion and nonmetricity:

$$S = \int d^4x \sqrt{-g} \left[ \mathcal{L}_m - \frac{1}{16\pi} \mathcal{L}_g(\tilde{\mathcal{R}}, \mathcal{T}, \mathcal{Q}) \right].$$

- Correspondence between geometry and matter:

$$\begin{aligned} \frac{\delta S_g}{\delta e^a{}_\nu} &= 16\pi \theta_a{}^\nu, \\ \frac{\delta S_g}{\delta \omega^a{}_{b\nu}} &= 16\pi \Delta_a{}^{b\nu}. \end{aligned}$$

Here  $\theta_a{}^\nu$  is the energy-momentum tensor (canonical) and  $\Delta_a{}^{b\nu}$  is the hypermomentum density tensor.

# Dynamics of metric-affine geometry

- Gravitational action with dynamical torsion and nonmetricity:

$$S = \int d^4x \sqrt{-g} \left[ \mathcal{L}_m - \frac{1}{16\pi} \mathcal{L}_g(\tilde{\mathcal{R}}, \mathcal{T}, \mathcal{Q}) \right].$$

- Correspondence between geometry and matter:

$$\frac{\delta S_g}{\delta e^a{}_\nu} = 16\pi \theta_a{}^\nu,$$
$$\frac{\delta S_g}{\delta \omega^a{}_{b\nu}} = 16\pi \Delta_a{}^{b\nu}.$$

Here  $\theta_a{}^\nu$  is the energy-momentum tensor (canonical) and  $\Delta_a{}^{b\nu}$  is the hypermomentum density tensor.

- $GL(4, R)$  group allows the definition of a large number of scalar invariants depending on the aforementioned tensors.

- General quadratic gravitational action with dynamical torsion and nonmetricity:

$$\begin{aligned}
 S = \int d^4x \sqrt{-g} \left\{ \mathcal{L}_m + \frac{1}{16\pi} \right. & \left[ -\tilde{R} + a_1 \tilde{R}^2 + a_2 \tilde{R}_{\lambda\rho\mu\nu} \tilde{R}^{\lambda\rho\mu\nu} + a_3 \tilde{R}_{\lambda\rho\mu\nu} \tilde{R}^{\rho\lambda\mu\nu} \right. \\
 & + a_4 \tilde{R}_{\lambda\rho\mu\nu} \tilde{R}^{\mu\nu\lambda\rho} + a_5 \tilde{R}_{\lambda\rho\mu\nu} \tilde{R}^{\lambda\mu\rho\nu} + a_6 \tilde{R}_{\lambda\rho\mu\nu} \tilde{R}^{\mu\lambda\rho\nu} + a_7 \tilde{R}_{\rho\lambda\mu\nu} \tilde{R}^{\mu\lambda\rho\nu} \\
 & + a_8 \tilde{R}_{\mu\nu} \tilde{R}^{\mu\nu} + a_9 \tilde{R}_{\mu\nu} \tilde{R}^{\nu\mu} + a_{10} \hat{R}_{\mu\nu} \hat{R}^{\mu\nu} + a_{11} \hat{R}_{\mu\nu} \hat{R}^{\nu\mu} + a_{12} \tilde{R}_{\mu\nu} \hat{R}^{\mu\nu} \\
 & + a_{13} \tilde{R}_{\mu\nu} \hat{R}^{\nu\mu} + a_{14} \tilde{R}^\lambda{}_{\lambda\mu\nu} \tilde{R}^\rho{}_{\rho}{}^{\mu\nu} + a_{15} \tilde{R}^\lambda{}_{\lambda\mu\nu} \tilde{R}^{\mu\nu} + a_{16} \tilde{R}^\lambda{}_{\lambda\mu\nu} \hat{R}^{\mu\nu} \\
 & + b_1 T_{\lambda\mu\nu} T^{\lambda\mu\nu} + b_2 T_{\lambda\mu\nu} T^{\mu\lambda\nu} + b_3 T^\lambda{}_{\lambda\nu} T^\mu{}_{\mu}{}^\nu + c_1 T_{\lambda\mu\nu} Q^{\mu\lambda\nu} \\
 & + c_2 T^\lambda{}_{\lambda\nu} Q^{\nu\mu}{}_{\mu} + c_3 T^\lambda{}_{\lambda\nu} Q^{\mu\nu}{}_{\mu} + d_1 Q_{\lambda\mu\nu} Q^{\lambda\mu\nu} + d_2 Q_{\lambda\mu\nu} Q^{\mu\lambda\nu} \\
 & \left. + d_3 Q^\lambda{}_{\lambda\nu} Q^\mu{}_{\mu}{}^\nu + d_4 Q_\nu{}^\lambda{}_{\lambda} Q^{\nu\mu}{}_{\mu} + d_5 Q^\lambda{}_{\lambda\nu} Q^{\nu\mu}{}_{\mu} \right] \left. \right\}.
 \end{aligned}$$

# Overview of the Talk

- 1 Introduction to Metric-affine gravity
  - Why modified gravity?
  - Basic geometrical quantities
- 2 Metric-Affine gravity
  - Curvature, torsion and nonmetricity
  - Dynamics
- 3 **MAG models with dynamical torsion and nonmetricity**
  - **Weyl part of nonmetricity**
  - **Axial symmetry in Weyl-Cartan geometry**
  - **Spherical symmetry with Shears and Weyl (complete nonmetricity)**

- Nonmetricity can be decomposed in the Weyl part plus a "traceless" part:

$$Q_{\lambda\mu\nu} = g_{\mu\nu}W_\lambda + \mathcal{Q}_{\lambda\mu\nu}.$$

where  $W_\mu = \frac{1}{4} Q_{\mu\nu}{}^\nu$ .

---

<sup>1</sup> S. Bahamonde and J. G. Valcarcel, JCAP **09**, 057 (2020).

<sup>2</sup> S. Bahamonde and J. G. Valcarcel, JCAP **01** (2022) no.01, 011.

- Nonmetricity can be decomposed in the Weyl part plus a "traceless" part:

$$Q_{\lambda\mu\nu} = g_{\mu\nu}W_\lambda + \mathcal{Q}_{\lambda\mu\nu}.$$

where  $W_\mu = \frac{1}{4} Q_{\mu\nu}{}^\nu$ .

- Quadratic gravitational action with dynamical torsion and nonmetricity in Weyl-Cartan geometry ( $Q_{\lambda\mu\nu} = g_{\mu\nu}W_\lambda$  and  $\mathcal{Q}_{\lambda\mu\nu} = 0$ )

$$S = \int d^4x \sqrt{-g} \left\{ \mathcal{L}_m + \frac{1}{64\pi} \left[ -4R - 6d_1 \tilde{R}_{\lambda[\rho\mu\nu]} \tilde{R}^{\lambda[\rho\mu\nu]} - 9d_1 \tilde{R}_{\lambda[\rho\mu\nu]} \tilde{R}^{\mu[\lambda\nu\rho]} + 8d_1 \tilde{R}_{[\mu\nu]} \tilde{R}^{[\mu\nu]} + \frac{1}{8} (32e_1 + 8e_2 + 17d_1) \tilde{R}^\lambda{}_{\lambda\mu\nu} \tilde{R}^\rho{}_{\rho}{}^{\mu\nu} - 7d_1 \tilde{R}_{[\mu\nu]} \tilde{R}^\lambda{}_{\lambda}{}^{\mu\nu} + 3(1 - 2a_2) T_{[\lambda\mu\nu]} T^{[\lambda\mu\nu]} \right] \right\}.$$

<sup>1</sup> S. Bahamonde and J. G. Valcarcel, JCAP **09**, 057 (2020).

<sup>2</sup> S. Bahamonde and J. G. Valcarcel, JCAP **01** (2022) no.01, 011.

- Nonmetricity can be decomposed in the Weyl part plus a "traceless" part:

$$Q_{\lambda\mu\nu} = g_{\mu\nu}W_\lambda + \mathcal{Q}_{\lambda\mu\nu}.$$

where  $W_\mu = \frac{1}{4} Q_{\mu\nu}{}^\nu$ .

- Quadratic gravitational action with dynamical torsion and nonmetricity in Weyl-Cartan geometry ( $Q_{\lambda\mu\nu} = g_{\mu\nu}W_\lambda$  and  $\mathcal{Q}_{\lambda\mu\nu} = 0$ )

$$S = \int d^4x \sqrt{-g} \left\{ \mathcal{L}_m + \frac{1}{64\pi} \left[ -4R - 6d_1 \tilde{R}_{\lambda[\rho\mu\nu]} \tilde{R}^{\lambda[\rho\mu\nu]} - 9d_1 \tilde{R}_{\lambda[\rho\mu\nu]} \tilde{R}^{\mu[\lambda\nu\rho]} + 8d_1 \tilde{R}_{[\mu\nu]} \tilde{R}^{[\mu\nu]} + \frac{1}{8} (32e_1 + 8e_2 + 17d_1) \tilde{R}^\lambda{}_{\lambda\mu\nu} \tilde{R}^\rho{}_{\rho}{}^{\mu\nu} - 7d_1 \tilde{R}_{[\mu\nu]} \tilde{R}^\lambda{}_{\lambda}{}^{\mu\nu} + 3(1 - 2a_2) T_{[\lambda\mu\nu]} T^{[\lambda\mu\nu]} \right] \right\}.$$

- Absence of a general Birkhoff's theorem in MAG: new spherically and axially symmetric vacuum solutions with independent dynamical torsion and nonmetricity fields<sup>1,2</sup>

<sup>1</sup> S. Bahamonde and J. G. Valcarcel, JCAP **09**, 057 (2020).

<sup>2</sup> S. Bahamonde and J. G. Valcarcel, JCAP **01** (2022) no.01, 011.

# Spherical symmetry

- Metric, torsion and nonmetricity in spherically symmetric space-times (#2 + #8 + #2 = #12):

$$\mathcal{L}_\xi g_{\mu\nu} = \mathcal{L}_\xi T^\lambda{}_{\mu\nu} = \mathcal{L}_\xi W_\mu = 0 \implies \mathcal{L}_\xi \tilde{R}_{\lambda\rho\mu\nu} = 0$$



# Spherical symmetry

- Metric, torsion and nonmetricity in spherically symmetric space-times (#2 + #8 + #2 = #12):

$$\mathcal{L}_\xi g_{\mu\nu} = \mathcal{L}_\xi T^\lambda{}_{\mu\nu} = \mathcal{L}_\xi W_\mu = 0 \implies \mathcal{L}_\xi \tilde{R}_{\lambda\rho\mu\nu} = 0$$

- By solving these equations we find that torsion and nonmetricity behave as

$$\begin{aligned} T^t{}_{tr} &= a(r), & T^r{}_{tr} &= b(r), & T^{\theta_k}{}_{t\theta_k} &= f(r), & T^{\theta_k}{}_{r\theta_k} &= g(r) \\ T^{\theta_k}{}_{t\theta_l} &= e^{a\theta_k} e^b{}_{\theta_l} \epsilon_{ab} d(r), & T^{\theta_k}{}_{r\theta_l} &= e^{a\theta_k} e^b{}_{\theta_l} \epsilon_{ab} h(r), \\ T^t{}_{\theta_k\theta_l} &= \epsilon_{kl} k(r) \sin\theta_1, & T^r{}_{\theta_k\theta_l} &= \epsilon_{kl} l(r) \sin\theta_1, \\ W_\lambda &= (w_1(r), w_2(r), 0, 0), \end{aligned}$$

whereas the metric is in the standard spherically symmetric form:

$$ds^2 = \Psi_1(r) dt^2 - \frac{dr^2}{\Psi_2(r)} - r^2 (d\theta_1^2 + \sin^2\theta_1 d\theta_2^2).$$

Here,  $\epsilon_{kl}$  is the Levi-Civita symbol in two dimensions.

# Solution with dilations and spin

- 1 The solution for the metric behaves as Reissner-Nordström

$$g_{tt} = -1/g_{rr} \equiv \Psi(r) = 1 - \frac{2m}{r} + \frac{d_1 \kappa_s^2 - 4e_1 \kappa_{d,e}^2}{r^2}.$$

# Solution with dilations and spin

- 1 The solution for the metric behaves as Reissner-Nordström

$$g_{tt} = -1/g_{rr} \equiv \Psi(r) = 1 - \frac{2m}{r} + \frac{d_1 \kappa_s^2 - 4e_1 \kappa_{d,e}^2}{r^2}.$$

- 2 Nonmetricity sector:

$$W_\mu = \frac{\kappa_{d,e}}{r} (1, -1/\Psi(r), 0, 0).$$

# Solution with dilations and spin

- 1 The solution for the metric behaves as Reissner-Nordström

$$g_{tt} = -1/g_{rr} \equiv \Psi(r) = 1 - \frac{2m}{r} + \frac{d_1 \kappa_s^2 - 4e_1 \kappa_{d,e}^2}{r^2}.$$

- 2 Nonmetricity sector:

$$W_\mu = \frac{\kappa_{d,e}}{r} (1, -1/\Psi(r), 0, 0).$$

- 3 Torsion sector:

$$\bar{S}^a = -\frac{\kappa_s}{r} (1, 1, 0, 0),$$
$$\bar{\mathcal{T}}_2^{abc} = \frac{\kappa_s}{3r} \begin{pmatrix} 0 & 0 & 0 & 0 & 0 & 0 & 2 \\ 0 & 0 & 0 & 0 & 0 & 0 & 2 \\ 0 & 0 & 1 & 0 & 0 & 1 & 0 \\ 0 & -1 & 0 & -1 & 0 & 0 & 0 \end{pmatrix}.$$

# What do these charges represent?

- **Torsion part:**

# What do these charges represent?

- **Torsion part:**

- 1 Intrinsic spin generates gravitation. This effect does not exist in GR.

# What do these charges represent?

- **Torsion part:**

- 1 Intrinsic spin generates gravitation. This effect does not exist in GR.
- 2 We know that the spin is a fundamental property of particles. Since their masses contribute to gravity, why their spin do not?

# What do these charges represent?

## ● Torsion part:

- 1 Intrinsic spin generates gravitation. This effect does not exist in GR.
- 2 We know that the spin is a fundamental property of particles. Since their masses contribute to gravity, why their spin do not?
- 3 The solution is in vacuum and a charge  $\kappa_s$  appears (spin charge). Analogue to the case of Schwarzschild where the mass  $M$  appears.



# What do these charges represent?

## ● Torsion part:

- 1 Intrinsic spin generates gravitation. This effect does not exist in GR.
- 2 We know that the spin is a fundamental property of particles. Since their masses contribute to gravity, why their spin do not?
- 3 The solution is in vacuum and a charge  $\kappa_s$  appears (spin charge). Analogue to the case of Schwarzschild where the mass  $M$  appears.
- 4 We expect that the spin charge might be important in certain astrophysical scenarios such as: highly magnetized neutron stars; supermassive black holes with endowed spin.

# What do these charges represent?

- **Nonmetricity part - only Weyl:**

# What do these charges represent?

- **Nonmetricity part - only Weyl:**

- ① Intrinsic dilations generates gravitation. This effect does not exist in GR.

# What do these charges represent?

- **Nonmetricity part - only Weyl:**

- ① Intrinsic dilations generates gravitation. This effect does not exist in GR.
- ② dilation: deformation that involves only change of volume (in this case, intrinsic dilation!)

# What do these charges represent?

## ● **Nonmetricity part - only Weyl:**

- 1 Intrinsic dilations generates gravitation. This effect does not exist in GR.
- 2 dilation: deformation that involves only change of volume (in this case, intrinsic dilation!)
- 3 Weyl part of nonmetricity is "scale invariant"

# What do these charges represent?

## ● **Nonmetricity part - only Weyl:**

- 1 Intrinsic dilations generates gravitation. This effect does not exist in GR.
- 2 dilation: deformation that involves only change of volume (in this case, intrinsic dilation!)
- 3 Weyl part of nonmetricity is "scale invariant"
- 4 Do all particles in nature have different dilations? is this property important in particle physics?

# Extension to axisymmetric space-times

- Metric, torsion and nonmetricity tensors in symmetric space-times:

$$\mathcal{L}_\xi g_{\mu\nu} = \mathcal{L}_\xi T^\lambda{}_{\mu\nu} = \mathcal{L}_\xi Q^\lambda{}_{\mu\nu} = 0 \implies \mathcal{L}_\xi \tilde{R}^\lambda{}_{\rho\mu\nu} = 0.$$

# Extension to axisymmetric space-times

- Metric, torsion and nonmetricity tensors in symmetric space-times:

$$\mathcal{L}_\xi g_{\mu\nu} = \mathcal{L}_\xi T^\lambda{}_{\mu\nu} = \mathcal{L}_\xi Q^\lambda{}_{\mu\nu} = 0 \implies \mathcal{L}_\xi \tilde{R}^\lambda{}_{\rho\mu\nu} = 0.$$

- Stationary and axisymmetric space-times:

$$\#10 \rightarrow \#4 \left\{ \begin{array}{l} ds^2 = \Psi_1(r, \vartheta) dt^2 - \frac{dr^2}{\Psi_2(r, \vartheta)} \\ - r^2 \Psi_3(r, \vartheta) \left[ d\vartheta^2 + \sin^2 \vartheta (d\varphi - \Psi_4(r, \vartheta) dt)^2 \right] \end{array} \right. ;$$

$$\#24 \left\{ T^\lambda{}_{\mu\nu} = T^\lambda{}_{\mu\nu}(r, \vartheta) \right.$$

$$\#4 \left\{ W_\mu = (W_t(r, \vartheta), W_r(r, \vartheta), W_\vartheta(r, \vartheta), W_\varphi(r, \vartheta)) \right\}.$$



- Rotating Kerr-Newman metric structure<sup>3</sup>:

$$ds^2 = \Psi(r, \vartheta) dt^2 - \frac{r^2 + a^2 \cos^2 \vartheta}{(r^2 + a^2 \cos^2 \vartheta) \Psi(r, \vartheta) + a^2 \sin^2 \vartheta} dr^2 \\ - (r^2 + a^2 \cos^2 \vartheta) d\vartheta^2 + 2a (1 - \Psi(r, \vartheta)) \sin^2 \vartheta dt d\varphi \\ - \sin^2 \vartheta [r^2 + a^2 + a^2 (1 - \Psi(r, \vartheta)) \sin^2 \vartheta] d\varphi^2 ,$$

$$\Psi(r, \vartheta) = 1 - \frac{[2mr + 4e_1(\kappa_{d,e}^2 + \kappa_{d,m}^2) - d_1 \kappa_s^2]}{r^2 + a^2 \cos^2 \vartheta} .$$

---

<sup>3</sup>S. Bahamonde and J. G. Valcarcel, JCAP **01** (2022) no.01, 011.

- Rotating Kerr-Newman metric structure<sup>3</sup>:

$$\begin{aligned}
 ds^2 = & \Psi(r, \vartheta) dt^2 - \frac{r^2 + a^2 \cos^2 \vartheta}{(r^2 + a^2 \cos^2 \vartheta) \Psi(r, \vartheta) + a^2 \sin^2 \vartheta} dr^2 \\
 & - (r^2 + a^2 \cos^2 \vartheta) d\vartheta^2 + 2a (1 - \Psi(r, \vartheta)) \sin^2 \vartheta dt d\varphi \\
 & - \sin^2 \vartheta [r^2 + a^2 + a^2 (1 - \Psi(r, \vartheta)) \sin^2 \vartheta] d\varphi^2,
 \end{aligned}$$

$$\Psi(r, \vartheta) = 1 - \frac{[2mr + 4e_1(\kappa_{d,e}^2 + \kappa_{d,m}^2) - d_1 \kappa_s^2]}{r^2 + a^2 \cos^2 \vartheta}.$$

- Field strength tensors:

$$\begin{aligned}
 \bar{R}_{[\mu\nu]} &= \frac{1}{12} \varepsilon^\lambda{}_{\sigma\mu\nu} \nabla_\lambda \bar{S}^\sigma + \frac{1}{2} \nabla_\lambda \bar{t}^\lambda{}_{\mu\nu}; \quad \tilde{R}^\lambda{}_{\lambda\mu\nu} = 4 \nabla_{[\nu} W_{\mu]}; \\
 \bar{R}^\lambda{}_{[\mu\nu\rho]} &= \frac{1}{6} \varepsilon^\lambda{}_{\sigma[\rho\nu} \nabla_{\mu]} \bar{S}^\sigma + \nabla_{[\mu} \bar{t}^\lambda{}_{\rho\nu]} + \frac{1}{4} \varepsilon^\lambda{}_{\omega\sigma[\rho} \dot{t}_1^{\sigma}{}_{\mu\nu]} \bar{S}^\omega \\
 &\quad - \frac{1}{18} \varepsilon_{\sigma\mu\nu\rho} \dot{T}_1^\lambda \bar{S}^\sigma.
 \end{aligned}$$

<sup>3</sup>S. Bahamonde and J. G. Valcarcel, JCAP **01** (2022) no.01, 011.

- Nonmetricity sector:(no approx.)

$$w_1(r, \vartheta) = \frac{\kappa_{d,e} r - a \kappa_{d,m} \cos \vartheta}{r^2 + a^2 \cos^2 \vartheta}, \quad w_3(r, \vartheta) = 0,$$

$$w_2(r, \vartheta) = - \frac{\kappa_{d,e} r}{(r^2 + a^2 \cos^2 \vartheta) \Psi(r, \vartheta) + a^2 \sin^2 \vartheta},$$

$$w_4(r, \vartheta) = \kappa_{d,m} \left( \frac{r^2 + a^2}{r^2 + a^2 \cos^2 \vartheta} \cos \vartheta - \gamma \right) - a \frac{\kappa_{d,e} r \sin^2 \vartheta}{r^2 + a^2 \cos^2 \vartheta}.$$

- Nonmetricity sector:(no approx.)

$$w_1(r, \vartheta) = \frac{\kappa_{d,e} r - a \kappa_{d,m} \cos \vartheta}{r^2 + a^2 \cos^2 \vartheta}, \quad w_3(r, \vartheta) = 0,$$

$$w_2(r, \vartheta) = - \frac{\kappa_{d,e} r}{(r^2 + a^2 \cos^2 \vartheta) \Psi(r, \vartheta) + a^2 \sin^2 \vartheta},$$

$$w_4(r, \vartheta) = \kappa_{d,m} \left( \frac{r^2 + a^2}{r^2 + a^2 \cos^2 \vartheta} \cos \vartheta - \gamma \right) - a \frac{\kappa_{d,e} r \sin^2 \vartheta}{r^2 + a^2 \cos^2 \vartheta}.$$

- Torsion sector (decoupling limit between the spin and the orbital angular momentum  $|a\kappa_s| \ll 1$ ):

$$\bar{S}^a = - \frac{\kappa_s}{r} (1, 1, 0, 0) + \mathcal{O}(a\kappa_s),$$

$$\bar{\mathcal{T}}_2^{abc} = \frac{\kappa_s}{3r} \begin{pmatrix} 0 & 0 & 0 & 0 & 0 & 2 \\ 0 & 0 & 0 & 0 & 0 & 2 \\ 0 & 0 & 1 & 0 & 1 & 0 \\ 0 & -1 & 0 & -1 & 0 & 0 \end{pmatrix} + \mathcal{O}(a\kappa_s).$$

# Gravitational spin-orbit interaction

- We found a solution in the decoupling limit  $a\kappa_s \ll 1$ , which ensures that the Maxwell equation and closure conditions are fulfilled by the field strength tensors of torsion

$$\nabla_\lambda \tilde{R}^\lambda{}_{[\rho\mu\nu]} = \nabla_\mu \tilde{R}^{[\mu\nu]} = 0, \quad \nabla_{[\sigma} \tilde{R}_{\lambda[\rho\mu\nu]} = \nabla_{[\lambda} \tilde{R}_{[\mu\nu]} = 0.$$

# Gravitational spin-orbit interaction

- We found a solution in the decoupling limit  $a\kappa_s \ll 1$ , which ensures that the Maxwell equation and closure conditions are fulfilled by the field strength tensors of torsion

$$\nabla_\lambda \tilde{R}^\lambda{}_{[\rho\mu\nu]} = \nabla_\mu \tilde{R}^{[\mu\nu]} = 0, \quad \nabla_{[\sigma} \tilde{R}_{\lambda[\rho\mu\nu]} = \nabla_{[\lambda} \tilde{R}_{[\mu\nu]} = 0.$$

# Gravitational spin-orbit interaction

- We found a solution in the decoupling limit  $a\kappa_s \ll 1$ , which ensures that the Maxwell equation and closure conditions are fulfilled by the field strength tensors of torsion

$$\nabla_\lambda \tilde{R}^\lambda{}_{[\rho\mu\nu]} = \nabla_\mu \tilde{R}^{[\mu\nu]} = 0, \quad \nabla_{[\sigma} \tilde{R}_{\lambda[\rho\mu\nu]} = \nabla_{[\lambda} \tilde{R}_{[\mu\nu]} = 0.$$

## Possible new effects in the decoupling limit

The dynamics of torsion and nonmetricity alters the geometry of the space-time  $\implies$

# Gravitational spin-orbit interaction

- We found a solution in the decoupling limit  $a\kappa_s \ll 1$ , which ensures that the Maxwell equation and closure conditions are fulfilled by the field strength tensors of torsion

$$\nabla_\lambda \tilde{R}^\lambda{}_{[\rho\mu\nu]} = \nabla_\mu \tilde{R}^{[\mu\nu]} = 0, \quad \nabla_{[\sigma} \tilde{R}_{\lambda[\rho\mu\nu]} = \nabla_{[\lambda} \tilde{R}_{[\mu\nu]} = 0.$$

## Possible new effects in the decoupling limit

The dynamics of torsion and nonmetricity alters the geometry of the space-time  $\implies$



# Gravitational spin-orbit interaction

- We found a solution in the decoupling limit  $a\kappa_s \ll 1$ , which ensures that the Maxwell equation and closure conditions are fulfilled by the field strength tensors of torsion

$$\nabla_\lambda \tilde{R}^\lambda{}_{[\rho\mu\nu]} = \nabla_\mu \tilde{R}^{[\mu\nu]} = 0, \quad \nabla_{[\sigma} \tilde{R}_{\lambda[\rho\mu\nu]]} = \nabla_{[\lambda} \tilde{R}_{[\mu\nu]]} = 0.$$

## Possible new effects in the decoupling limit

The dynamics of torsion and nonmetricity alters the geometry of the space-time  $\implies$  Additional modifications provided by a strong coupling between the orbital and the spin angular.

# Gravitational spin-orbit interaction

- We found a solution in the decoupling limit  $a\kappa_s \ll 1$ , which ensures that the Maxwell equation and closure conditions are fulfilled by the field strength tensors of torsion

$$\nabla_\lambda \tilde{R}^\lambda{}_{[\rho\mu\nu]} = \nabla_\mu \tilde{R}^{[\mu\nu]} = 0, \quad \nabla_{[\sigma} \tilde{R}_{\lambda[\rho\mu\nu]]} = \nabla_{[\lambda} \tilde{R}_{[\mu\nu]]} = 0.$$

## Possible new effects in the decoupling limit

The dynamics of torsion and nonmetricity alters the geometry of the space-time  $\implies$  Additional modifications provided by a strong coupling between the orbital and the spin angular.

# Gravitational spin-orbit interaction

- We found a solution in the decoupling limit  $a\kappa_s \ll 1$ , which ensures that the Maxwell equation and closure conditions are fulfilled by the field strength tensors of torsion

$$\nabla_\lambda \tilde{R}^\lambda{}_{[\rho\mu\nu]} = \nabla_\mu \tilde{R}^{[\mu\nu]} = 0, \quad \nabla_{[\sigma} \tilde{R}_{\lambda[\rho\mu\nu]} = \nabla_{[\lambda} \tilde{R}_{[\mu\nu]} = 0.$$

## Possible new effects in the decoupling limit

The dynamics of torsion and nonmetricity alters the geometry of the space-time  $\implies$  Additional modifications provided by a strong coupling between the orbital and the spin angular.

- **Gravitational spin-orbit interaction:**

$$\mathcal{H}_{\text{LS}} = \frac{1}{m_e^2 r} \frac{\partial V}{\partial r} \mathbf{L} \cdot \mathbf{S} \approx \frac{d_1}{2r} \frac{\partial g_{tt}}{\partial r} a\kappa_s \cos \vartheta$$

- It is well known that the most general axisymmetric system in vacuum that can describe a BH type D in **GR** contains<sup>4</sup>:

<b>Mass</b>	$M$
<b>Angular momentum</b>	$a$
<b>Taub-NUT charge</b>	$l$
<b>Acceleration</b>	$\alpha$

---

<sup>4</sup>J. F. Plebanski and M. Demianski, Annals Phys. **98** (1976), 98-127

- It is well known that the most general axisymmetric system in vacuum that can describe a BH type D in **GR** contains<sup>4</sup>:

<b>Mass</b>	$M$
<b>Angular momentum</b>	$a$
<b>Taub-NUT charge</b>	$l$
<b>Acceleration</b>	$\alpha$

- Further, one can add a cosmological constant  $\Lambda$  and a electric charge  $q_e$  and magnetic charge  $q_m$ .

---

<sup>4</sup>J. F. Plebanski and M. Demianski, Annals Phys. **98** (1976), 98-127

- It is well known that the most general axisymmetric system in vacuum that can describe a BH type D in **GR** contains<sup>4</sup>:

<b>Mass</b>	$M$
<b>Angular momentum</b>	$a$
<b>Taub-NUT charge</b>	$l$
<b>Acceleration</b>	$\alpha$

- Further, one can add a cosmological constant  $\Lambda$  and a electric charge  $q_e$  and magnetic charge  $q_m$ .
- The solution in GR is called Plebanski-Damianski solution.

---

<sup>4</sup>J. F. Plebanski and M. Demianski, Annals Phys. **98** (1976), 98-127

- The Plebanski-Damianski metric was recently presented in an improved form with  $\Lambda = 0$  in by Podolský and Vrátný (Phys. Rev. D **104** (2021), 084078), and it can be written as

$$ds^2 = \Omega^{-2}(r, \vartheta) \left\{ \Phi_1(r, \vartheta) [dt - (a \sin^2 \vartheta + 2l(\chi - \cos \vartheta)) d\varphi]^2 - \frac{dr^2}{\Phi_1(r, \vartheta)} - \frac{d\vartheta^2}{\Phi_2(r, \vartheta)} - \Phi_2(r, \vartheta) \sin^2 \vartheta [a dt - (r^2 + a^2 + l^2 + 2\chi al) d\varphi]^2 \right\}.$$

where  $\Phi_i, \Omega$  are cumbersome functions depending on these parameters.

---

<sup>5</sup>S. Bahamonde, J. G. Valcarcel and L. Järv, JCAP **04** (2022) no.04, 011.

- The Plebanski-Damianski metric was recently presented in an improved form with  $\Lambda = 0$  in by Podolský and Vrátný (Phys. Rev. D **104** (2021), 084078), and it can be written as

$$ds^2 = \Omega^{-2}(r, \vartheta) \left\{ \Phi_1(r, \vartheta) [dt - (a \sin^2 \vartheta + 2l(\chi - \cos \vartheta)) d\varphi]^2 - \frac{dr^2}{\Phi_1(r, \vartheta)} - \frac{d\vartheta^2}{\Phi_2(r, \vartheta)} - \Phi_2(r, \vartheta) \sin^2 \vartheta [a dt - (r^2 + a^2 + l^2 + 2\chi al) d\varphi]^2 \right\}.$$

where  $\Phi_i, \Omega$  are cumbersome functions depending on these parameters.

- We just found this new form with the cosmological constant<sup>5</sup> with  $\Phi_1(r, \vartheta) = \frac{Q(r)}{\rho^2(r, \vartheta)}$ ,  $\Phi_2(r, \vartheta) = \frac{P(\vartheta)}{\rho^2(r, \vartheta)}$ , and  $\rho^2(r, \vartheta) = r^2 + (a \cos \vartheta + l)^2$ . Here,  $Q(r), \Omega(\vartheta)$  include the PD quantities.

<sup>5</sup>S. Bahamonde, J. G. Valcarcel and L. Järvi, JCAP **04** (2022) no.04, 011.



- We found a solution to **OUR THEORY** in the decoupling limit  $|x_i \kappa_s| \ll 1$  with  $x = (a, l, \alpha)$  with additional torsion and nonmetricity terms

- We found a solution to **OUR THEORY** in the decoupling limit  $|x_i \kappa_s| \ll 1$  with  $x = (a, l, \alpha)$  with additional torsion and nonmetricity terms

- We found a solution to **OUR THEORY** in the decoupling limit  $|x_i \kappa_s| \ll 1$  with  $x = (a, l, \alpha)$  with additional torsion and nonmetricity terms

$$w_1(r, \vartheta) = \frac{\kappa_{d,e} r - \kappa_{d,m} (a \cos \vartheta + l)}{r^2 + (a \cos \vartheta + l)^2}, \quad w_2(r, \vartheta) = -\frac{\kappa_{d,e} r - \kappa_{d,m} (a \gamma + l)}{Q(r)},$$

$$w_3(r, \vartheta) = -\kappa_{d,m} \sqrt{K(\vartheta) - \left( \frac{\cot \vartheta - \gamma \csc \vartheta}{P(\vartheta)} \right)^2},$$

$$w_4(r, \vartheta) = \kappa_{d,m} \left[ \frac{(r^2 + a^2 - l^2) \cos \vartheta + a l \sin^2 \vartheta + 2\chi l (a \cos \vartheta + l)}{r^2 + (a \cos \vartheta + l)^2} - \gamma \right] - \frac{\kappa_{d,e} r [a \sin^2 \vartheta + 2l (\chi - \cos \vartheta)]}{r^2 + (a \cos \vartheta + l)^2},$$

$$\bar{T}^\vartheta{}_{\varphi t} = -\bar{T}^\varphi{}_{\vartheta t} \sin^2 \vartheta = -\bar{T}^\vartheta{}_{\varphi r} \frac{Q(r)}{\rho^2(r, \vartheta)} = \bar{T}^\varphi{}_{\vartheta r} \frac{Q(r)}{\rho^2(r, \vartheta)} \sin^2 \vartheta = \frac{\kappa_s \sin \vartheta}{r} + \mathcal{O}(x_i \kappa_s).$$

- Similarly as electromagnetism, the torsion behaves as a Coulomb-like quantity depending on a spin charge  $\kappa_s$  and the non-metricity on the dilation charge  $\kappa_d$ .

# Nonmetricity decomposition

- Nonmetricity can be decomposed in the Weyl part plus a "traceless" part:

$$Q_{\lambda\mu\nu} = g_{\mu\nu}W_\lambda + \mathcal{Q}_{\lambda\mu\nu}.$$

where

$$W_\mu = \frac{1}{4} Q_{\mu\nu}{}^\nu,$$
$$\mathcal{Q}_{\lambda\mu\nu} = g_{\lambda(\mu}\Lambda_{\nu)} - \frac{1}{4}g_{\mu\nu}\Lambda_\lambda + \frac{1}{3}\varepsilon_{\lambda\rho\sigma(\mu}\Omega_{\nu)}{}^{\rho\sigma} + q_{\lambda\mu\nu},$$

# Nonmetricity decomposition

- Nonmetricity can be decomposed in the Weyl part plus a "traceless" part:

$$Q_{\lambda\mu\nu} = g_{\mu\nu}W_{\lambda} + \mathcal{Q}_{\lambda\mu\nu}.$$

where

$$W_{\mu} = \frac{1}{4} Q_{\mu\nu}{}^{\nu},$$
$$\mathcal{Q}_{\lambda\mu\nu} = g_{\lambda(\mu}\Lambda_{\nu)} - \frac{1}{4}g_{\mu\nu}\Lambda_{\lambda} + \frac{1}{3}\varepsilon_{\lambda\rho\sigma(\mu}\Omega_{\nu)}{}^{\rho\sigma} + q_{\lambda\mu\nu},$$

- We defined a vector, and two traceless and pseudotraceless tensors

$$\Lambda_{\mu} = \frac{4}{9} (Q^{\nu}{}_{\mu\nu} - W_{\mu}),$$
$$\Omega_{\lambda}{}^{\mu\nu} = - \left[ \varepsilon^{\mu\nu\rho\sigma} Q_{\rho\sigma\lambda} + \varepsilon^{\mu\nu\rho}{}_{\lambda} \left( \frac{3}{4}\Lambda_{\rho} - W_{\rho} \right) \right],$$
$$q_{\lambda\mu\nu} = Q_{(\lambda\mu\nu)} - g_{(\mu\nu}W_{\lambda)} - \frac{3}{4}g_{(\mu\nu}\Lambda_{\lambda)},$$

# The traceless part of nonmetricity and shears

- If this quantity is different to zero, when we parallel transport a vector, not only its norm changes but also its angle.

# The traceless part of nonmetricity and shears

- If this quantity is different to zero, when we parallel transport a vector, not only its norm changes but also its angle.
- It is invariant under shears transformations.

# The traceless part of nonmetricity and shears

- If this quantity is different to zero, when we parallel transport a vector, not only its norm changes but also its angle.
- It is invariant under shears transformations.
- Shears: Deformations without changing the volume.



# The traceless part of nonmetricity and shears

- If this quantity is different to zero, when we parallel transport a vector, not only its norm changes but also its angle.
- It is invariant under shears transformations.
- Shears: Deformations without changing the volume.
- Up to now, there are not exact solutions with shears in MAG.

# MAG theory with shears

- Let us first consider a simple model where torsion is not propagating and the traceless part of nonmetricity is dynamical:

$$S = \frac{1}{16\pi} \int d^4x \sqrt{-g} \left[ -R + 2f_1 \tilde{R}_{(\lambda\rho)\mu\nu} \tilde{R}^{(\lambda\rho)\mu\nu} + 2f_2 \left( \tilde{R}_{(\mu\nu)} - \hat{R}_{(\mu\nu)} \right) \left( \tilde{R}^{(\mu\nu)} - \hat{R}^{(\mu\nu)} \right) \right],$$

# MAG theory with shears

- Let us first consider a simple model where torsion is not propagating and the traceless part of nonmetricity is dynamical:

$$S = \frac{1}{16\pi} \int d^4x \sqrt{-g} \left[ -R + 2f_1 \tilde{R}_{(\lambda\rho)\mu\nu} \tilde{R}^{(\lambda\rho)\mu\nu} + 2f_2 \left( \tilde{R}_{(\mu\nu)} - \hat{R}_{(\mu\nu)} \right) \left( \tilde{R}^{(\mu\nu)} - \hat{R}^{(\mu\nu)} \right) \right],$$

- As can be seen, the propagation of the nonmetricity field described in the action is carried out by the symmetric part of the curvature tensor and its symmetric contraction:

$$\begin{aligned} \tilde{R}^{(\lambda\rho)}_{\mu\nu} &= \tilde{\nabla}_{[\nu} Q_{\mu]}^{\lambda\rho} + \frac{1}{2} T^{\sigma}_{\mu\nu} Q_{\sigma}^{\lambda\rho}, \\ \tilde{R}_{(\mu\nu)} - \hat{R}_{(\mu\nu)} &= \tilde{\nabla}_{(\mu} Q^{\lambda}_{\nu)\lambda} - \tilde{\nabla}_{\lambda} Q_{(\mu\nu)}^{\lambda} - Q^{\lambda\rho}_{\lambda} Q_{(\mu\nu)\rho} + Q_{\lambda\rho(\mu} Q_{\nu)}^{\lambda\rho} \\ &\quad + T_{\lambda\rho(\mu} Q^{\lambda\rho}_{\nu)}, \end{aligned}$$

which in turn constitute deviations from the third Bianchi of GR.

- As can be seen, the propagation of the nonmetricity field described in the action is carried out by the symmetric part of the curvature tensor and its symmetric contraction:

$$\begin{aligned}\tilde{R}^{(\lambda\rho)}{}_{\mu\nu} &= \tilde{\nabla}_{[\nu} Q_{\mu]}{}^{\lambda\rho} + \frac{1}{2} T^{\sigma}{}_{\mu\nu} Q_{\sigma}{}^{\lambda\rho}, \\ \tilde{R}_{(\mu\nu)} - \hat{R}_{(\mu\nu)} &= \tilde{\nabla}_{(\mu} Q^{\lambda}{}_{\nu)\lambda} - \tilde{\nabla}_{\lambda} Q_{(\mu\nu)}{}^{\lambda} - Q^{\lambda\rho}{}_{\lambda} Q_{(\mu\nu)\rho} + Q_{\lambda\rho(\mu} Q_{\nu)}{}^{\lambda\rho} \\ &\quad + T_{\lambda\rho(\mu} Q^{\lambda\rho}{}_{\nu)},\end{aligned}$$

which in turn constitute deviations from the third Bianchi of GR.

# Spherical symmetry with nonmetricity and torsion

- Metric, torsion and nonmetricity in spherically symmetric space-times (#2 + #8 + #12 = #22):

$$\mathcal{L}_\xi g_{\mu\nu} = \mathcal{L}_\xi T^\lambda{}_{\mu\nu} = \mathcal{L}_\xi Q_{\alpha\mu\nu} = 0 \implies \mathcal{L}_\xi \tilde{R}_{\lambda\rho\mu\nu} = 0$$

# Spherical symmetry with nonmetricity and torsion

- Metric, torsion and nonmetricity in spherically symmetric space-times (#2 + #8 + #12 = #22):

$$\mathcal{L}_\xi g_{\mu\nu} = \mathcal{L}_\xi T^\lambda{}_{\mu\nu} = \mathcal{L}_\xi Q_{\alpha\mu\nu} = 0 \implies \mathcal{L}_\xi \tilde{R}_{\lambda\rho\mu\nu} = 0$$

- Nonmetricity now contains all the 12 dof:

$$\begin{aligned} Q_{ttt} &= q_1(r), & Q_{trr} &= q_2(r), & Q_{ttr} &= q_3(r), \\ Q_{t\vartheta\vartheta} &= Q_{t\varphi\varphi} \csc^2 \vartheta = q_4(r), & Q_{rtt} &= q_5(r), & Q_{rrr} &= q_6(r), \\ Q_{rtr} &= q_7(r), & Q_{r\vartheta\vartheta} &= Q_{r\varphi\varphi} \csc^2 \vartheta = q_8(r), \\ Q_{\vartheta t\vartheta} &= Q_{\varphi t\varphi} \csc^2 \vartheta = q_9(r), & Q_{\vartheta r\vartheta} &= Q_{\varphi r\varphi} \csc^2 \vartheta = q_{10}(r), \\ Q_{\vartheta t\varphi} &= -Q_{\varphi t\vartheta} = q_{11}(r) \sin \vartheta, & Q_{\vartheta r\varphi} &= -Q_{\varphi r\vartheta} = q_{12}(r) \sin \vartheta, \end{aligned}$$

whereas the metric and torsion are the same as before.

# How to find a solution with all of these dof?

- We are only interested in the traceless part of  $Q_{\alpha\mu\nu}$  (containing shears), so that:

# How to find a solution with all of these dof?

- We are only interested in the traceless part of  $Q_{\alpha\mu\nu}$  (containing shears), so that:
  - ① We eliminate the Weyl part of nonmetricity  $W_\mu = \frac{1}{4} Q_{\mu\nu}{}^\nu = 0$  by setting

$$q_1(r) = \frac{\Psi_1(r)}{r^2} (r^2 q_2(r) \Psi_2(r) + 2q_4(r)) ,$$

$$q_5(r) = \frac{\Psi_1(r)}{r^2} (r^2 q_6(r) \Psi_2(r) + 2q_8(r)) .$$



# How to find a solution with all of these dof?

- We are only interested in the traceless part of  $Q_{\alpha\mu\nu}$  (containing shears), so that:

- ① We eliminate the Weyl part of nonmetricity  $W_\mu = \frac{1}{4} Q_{\mu\nu}{}^\nu = 0$  by setting

$$q_1(r) = \frac{\Psi_1(r)}{r^2} (r^2 q_2(r) \Psi_2(r) + 2q_4(r)) ,$$

$$q_5(r) = \frac{\Psi_1(r)}{r^2} (r^2 q_6(r) \Psi_2(r) + 2q_8(r)) .$$

- ② We imposed  $N_{[\lambda\rho]\mu} = 0$  which is equivalent to  $T_{\lambda\mu\nu} = Q_{[\mu\nu]\lambda}$ :  
→ Shear transformations in the general linear group involves the part of the anholonomic connection describing a shear current or charge to take values in the **symmetric traceless part** of the Lie algebra.

# How to find a solution with all of these dof?

- We are only interested in the traceless part of  $Q_{\alpha\mu\nu}$  (containing shears), so that:

- ① We eliminate the Weyl part of nonmetricity  $W_\mu = \frac{1}{4} Q_{\mu\nu}{}^\nu = 0$  by setting

$$q_1(r) = \frac{\Psi_1(r)}{r^2} (r^2 q_2(r) \Psi_2(r) + 2q_4(r)) ,$$

$$q_5(r) = \frac{\Psi_1(r)}{r^2} (r^2 q_6(r) \Psi_2(r) + 2q_8(r)) .$$

- ② We imposed  $N_{[\lambda\rho]\mu} = 0$  which is equivalent to  $T_{\lambda\mu\nu} = Q_{[\mu\nu]\lambda}$ :  
→ Shear transformations in the general linear group involves the part of the anholonomic connection describing a shear current or charge to take values in the **symmetric traceless part** of the Lie algebra.
- ③ We demand the corresponding torsion and nonmetricity scalars of the solution to be regular.

# How to find a solution with all of these dof?

- We are only interested in the traceless part of  $Q_{\alpha\mu\nu}$  (containing shears), so that:

- ① We eliminate the Weyl part of nonmetricity  $W_\mu = \frac{1}{4} Q_{\mu\nu}{}^\nu = 0$  by setting

$$q_1(r) = \frac{\Psi_1(r)}{r^2} (r^2 q_2(r) \Psi_2(r) + 2q_4(r)) ,$$

$$q_5(r) = \frac{\Psi_1(r)}{r^2} (r^2 q_6(r) \Psi_2(r) + 2q_8(r)) .$$

- ② We imposed  $N_{[\lambda\rho]\mu} = 0$  which is equivalent to  $T_{\lambda\mu\nu} = Q_{[\mu\nu]\lambda}$ :  
→ Shear transformations in the general linear group involves the part of the anholonomic connection describing a shear current or charge to take values in the **symmetric traceless part** of the Lie algebra.
- ③ We demand the corresponding torsion and nonmetricity scalars of the solution to be regular.
- After following these three steps we end up with 2 dof (metric)+ 5 dof (torsion/nonmetricity) which is only 7 dof.

## New solution only with shears

- By plugging these conditions in the field equations, there are several branches but only one has solutions with dynamical shears. This branch involves the constants of the theory as

$$f_2 = -\frac{1}{4}f_1.$$

## New solution only with shears

- By plugging these conditions in the field equations, there are several branches but only one has solutions with dynamical shears. This branch involves the constants of the theory as

$$f_2 = -\frac{1}{4}f_1.$$

- The form of  $q_i$  and  $t_i$  is involved. One component of nonmetricity is arbitrary! (problem!)

## New solution only with shears

- By plugging these conditions in the field equations, there are several branches but only one has solutions with dynamical shears. This branch involves the constants of the theory as

$$f_2 = -\frac{1}{4}f_1.$$

- The form of  $q_i$  and  $t_i$  is involved. One component of nonmetricity is arbitrary! (problem!)
- The metric behaves as

$$ds^2 = \Psi_1(r) dt^2 - \frac{dr^2}{\Psi_2(r)} - r^2 (d\theta_1^2 + \sin^2 \theta_1 d\theta_2^2) .$$

with

$$\Psi_1(r) = \Psi_2(r) = 1 - \frac{2m}{r} - \frac{2f_1 \kappa_{\text{sh}}^2}{r^2} ,$$

where  $\kappa_{\text{sh}}$  is interpreted as a new charge, "shear charge".

- After finding the shear part alone, we found a theory having the first solution (with spin+dilation) plus the second (with only shears).

- After finding the shear part alone, we found a theory having the first solution (with spin+dilation) plus the second (with only shears).
- The action of the full model is

$$\begin{aligned}
 S = \frac{1}{64\pi} \int & \left[ -4R - 6d_1 \tilde{R}_{\lambda[\rho\mu\nu]} \tilde{R}^{\lambda[\rho\mu\nu]} - 9d_1 \tilde{R}_{\lambda[\rho\mu\nu]} \tilde{R}^{\mu[\lambda\nu\rho]} \right. \\
 & + 2d_1 \left( \tilde{R}_{[\mu\nu]} + \hat{R}_{[\mu\nu]} \right) \left( \tilde{R}^{[\mu\nu]} + \hat{R}^{[\mu\nu]} \right) + 18d_1 \tilde{R}_{\lambda[\rho\mu\nu]} \tilde{R}^{(\lambda\rho)\mu\nu} \\
 & - 3d_1 \tilde{R}_{(\lambda\rho)\mu\nu} \tilde{R}^{(\lambda\rho)\mu\nu} + 6d_1 \tilde{R}_{(\lambda\rho)\mu\nu} \tilde{R}^{(\lambda\mu)\rho\nu} + 2(2e_1 - f_1) \tilde{R}^\lambda{}_{\lambda\mu\nu} \tilde{R}^\rho{}_{\rho}{}^{\mu\nu} \\
 & + 8f_1 \tilde{R}_{(\lambda\rho)\mu\nu} \tilde{R}^{(\lambda\rho)\mu\nu} - 2f_1 \left( \tilde{R}_{(\mu\nu)} - \hat{R}_{(\mu\nu)} \right) \left( \tilde{R}^{(\mu\nu)} - \hat{R}^{(\mu\nu)} \right) \\
 & \left. + 3(1 - 2a_2) T_{[\lambda\mu\nu]} T^{[\lambda\mu\nu]} \right] d^4x \sqrt{-g}.
 \end{aligned}$$



- After finding the shear part alone, we found a theory having the first solution (with spin+dilation) plus the second (with only shears).
- The action of the full model is

$$\begin{aligned}
 S = \frac{1}{64\pi} \int & \left[ -4R - 6d_1 \tilde{R}_{\lambda[\rho\mu\nu]} \tilde{R}^{\lambda[\rho\mu\nu]} - 9d_1 \tilde{R}_{\lambda[\rho\mu\nu]} \tilde{R}^{\mu[\lambda\nu\rho]} \right. \\
 & + 2d_1 \left( \tilde{R}_{[\mu\nu]} + \hat{R}_{[\mu\nu]} \right) \left( \tilde{R}^{[\mu\nu]} + \hat{R}^{[\mu\nu]} \right) + 18d_1 \tilde{R}_{\lambda[\rho\mu\nu]} \tilde{R}^{(\lambda\rho)\mu\nu} \\
 & - 3d_1 \tilde{R}_{(\lambda\rho)\mu\nu} \tilde{R}^{(\lambda\rho)\mu\nu} + 6d_1 \tilde{R}_{(\lambda\rho)\mu\nu} \tilde{R}^{(\lambda\mu)\rho\nu} + 2(2e_1 - f_1) \tilde{R}^\lambda{}_{\lambda\mu\nu} \tilde{R}^{\rho\mu\nu} \\
 & + 8f_1 \tilde{R}_{(\lambda\rho)\mu\nu} \tilde{R}^{(\lambda\rho)\mu\nu} - 2f_1 \left( \tilde{R}_{(\mu\nu)} - \hat{R}_{(\mu\nu)} \right) \left( \tilde{R}^{(\mu\nu)} - \hat{R}^{(\mu\nu)} \right) \\
 & \left. + 3(1 - 2a_2) T_{[\lambda\mu\nu]} T^{[\lambda\mu\nu]} \right] d^4x \sqrt{-g}.
 \end{aligned}$$

- When traceless part of nonmetricity is zero, the above action coincides with the first one.

- Since we already found the solution for each model independently, it is not so difficult to find that the solution for the full model.

- Since we already found the solution for each model independently, it is not so difficult to find that the solution for the full model.
- In this case, all nonmetricity components are fully set by the field equations (remember that in the shear case, one component was free)

- Since we already found the solution for each model independently, it is not so difficult to find that the solution for the full model.
- In this case, all nonmetricity components are fully set by the field equations (remember that in the shear case, one component was free)
- The solution gives us the following metric

$$ds^2 = \Psi_1(r) dt^2 - \frac{dr^2}{\Psi_2(r)} - r^2 (d\theta_1^2 + \sin^2 \theta_1 d\theta_2^2) .$$

with

$$\Psi_1(r) = \Psi_2(r) = 1 - \frac{2m}{r} + \frac{d_1 \kappa_s^2 - 4e_1 \kappa_d^2 - 2f_1 \kappa_{sh}^2}{r^2} ,$$

having the three possible charges: spin, dilation and shear.

- On the other hand, the solution can also be trivially generalised to include the cosmological constant and Coulomb electromagnetic fields with electric and magnetic charges  $q_e$  and  $q_m$ , which are decoupled from torsion under the assumption of the minimal coupling principle. This natural extension is then described by a Reissner-Nordström-de Sitter-like geometry

$$\Psi(r) = 1 - \frac{2m}{r} + \frac{d_1 \kappa_s^2 - 4e_1 \kappa_d^2 - 2f_1 \kappa_{sh}^2 + q_e^2 + q_m^2}{r^2} + \frac{\Lambda}{3} r^2,$$

which turns out to represent **the broadest family of static and spherically symmetric black hole solutions obtained in MAG** so far.

# Conclusions and what do to next

- We found the first solutions with dynamical torsion and nonmetricity. First with the Weyl and then with the traceless part of nonmetricity.

# Conclusions and what do to next

- We found the first solutions with dynamical torsion and nonmetricity. First with the Weyl and then with the traceless part of nonmetricity.
- We found the correspondence of Plebansky-Damianski solution in our theory in the decoupling limit.

# Conclusions and what do to next

- We found the first solutions with dynamical torsion and nonmetricity. First with the Weyl and then with the traceless part of nonmetricity.
- We found the correspondence of Plebansky-Damianski solution in our theory in the decoupling limit.
- The general solution contains the three fundamental charges (spin,dilation and shear) and the mass which constitute the most general spherically symmetric solution with all the possible intrinsic geometrical properties of matter.



# Conclusions and what do to next

- We found the first solutions with dynamical torsion and nonmetricity. First with the Weyl and then with the traceless part of nonmetricity.
- We found the correspondence of Plebansky-Damianski solution in our theory in the decoupling limit.
- The general solution contains the three fundamental charges (spin, dilation and shear) and the mass which constitute the most general spherically symmetric solution with all the possible intrinsic geometrical properties of matter.
- It is worth studying:

# Conclusions and what do to next

- We found the first solutions with dynamical torsion and nonmetricity. First with the Weyl and then with the traceless part of nonmetricity.
- We found the correspondence of Plebansky-Damianski solution in our theory in the decoupling limit.
- The general solution contains the three fundamental charges (spin, dilation and shear) and the mass which constitute the most general spherically symmetric solution with all the possible intrinsic geometrical properties of matter.
- It is worth studying:
  - 1 Cosmology of the complete model: from inflation to dark energy.

# Conclusions and what do to next

- We found the first solutions with dynamical torsion and nonmetricity. First with the Weyl and then with the traceless part of nonmetricity.
- We found the correspondence of Plebansky-Damianski solution in our theory in the decoupling limit.
- The general solution contains the three fundamental charges (spin,dilation and shear) and the mass which constitute the most general spherically symmetric solution with all the possible intrinsic geometrical properties of matter.
- It is worth studying:
  - 1 Cosmology of the complete model: from inflation to dark energy.
  - 2 Perturbations of this solution: Is it stable? quasinormal modes?

# Conclusions and what do to next

- We found the first solutions with dynamical torsion and nonmetricity. First with the Weyl and then with the traceless part of nonmetricity.
- We found the correspondence of Plebansky-Damianski solution in our theory in the decoupling limit.
- The general solution contains the three fundamental charges (spin, dilation and shear) and the mass which constitute the most general spherically symmetric solution with all the possible intrinsic geometrical properties of matter.
- It is worth studying:
  - 1 Cosmology of the complete model: from inflation to dark energy.
  - 2 Perturbations of this solution: Is it stable? quasinormal modes?
  - 3 What is the role of dilations/shears in particle physics?