

# Theories with torsion and nonmetricity: basic concepts and what's next

Sebastián Bahamonde

Postdoctoral Researcher at Kavli IPMU, University of Tokyo, Japan

IBS Group meeting, 11/March/2025



- 1 General descriptions of theories with torsion and nonmetricity
- 2 The gauge approach of gravity: Poincare gauge theory
- 3 Fallacies of torsion
- 4 Poincare gauge gravity: Stability and theory
- 5 Black holes
  - Spherically symmetric black holes
  - Axially symmetric black holes
- 6 Cosmology

# Overview of the Talk

- 1 General descriptions of theories with torsion and nonmetricity
- 2 The gauge approach of gravity: Poincare gauge theory
- 3 Fallacies of torsion
- 4 Poincare gauge gravity: Stability and theory
- 5 Black holes
  - Spherically symmetric black holes
  - Axially symmetric black holes
- 6 Cosmology

# General descriptions

- Pseudo-Riemannian geometry (as in GR) assumes that our manifold contains curvature (and nothing more).

# General descriptions

- Pseudo-Riemannian geometry (as in GR) assumes that our manifold contains curvature (and nothing more).
- This assumption automatically gives us a unique connection: Levi-Civita connection  $\Gamma^{\lambda}_{\mu\nu}$  that is completely defined in terms of a metric  $g_{\mu\nu}$ .

# General descriptions

- Pseudo-Riemannian geometry (as in GR) assumes that our manifold contains curvature (and nothing more).
- This assumption automatically gives us a unique connection: Levi-Civita connection  $\Gamma^{\lambda}_{\mu\nu}$  that is completely defined in terms of a metric  $g_{\mu\nu}$ .
- Curvature  $R^{\lambda}_{\rho\mu\nu}$  and all other geometrical quantities (like Weyl) are NOT independent quantities: The metric tensor fully determines them.

# General descriptions

- Pseudo-Riemannian geometry (as in GR) assumes that our manifold contains curvature (and nothing more).
- This assumption automatically gives us a unique connection: Levi-Civita connection  $\Gamma^{\lambda}_{\mu\nu}$  that is completely defined in terms of a metric  $g_{\mu\nu}$ .
- Curvature  $R^{\lambda}_{\rho\mu\nu}$  and all other geometrical quantities (like Weyl) are NOT independent quantities: The metric tensor fully determines them.
- We aim to construct consistent new theories of gravity with new effects by modifying the geometry.

# General descriptions

- Pseudo-Riemannian geometry (as in GR) assumes that our manifold contains curvature (and nothing more).
- This assumption automatically gives us a unique connection: Levi-Civita connection  $\Gamma^{\lambda}_{\mu\nu}$  that is completely defined in terms of a metric  $g_{\mu\nu}$ .
- Curvature  $R^{\lambda}_{\rho\mu\nu}$  and all other geometrical quantities (like Weyl) are NOT independent quantities: The metric tensor fully determines them.
- We aim to construct consistent new theories of gravity with new effects by modifying the geometry.
- By doing that, the metric is no longer the only independent quantity, but now the general affine connection  $\tilde{\Gamma}^{\lambda}_{\mu\nu}$  is also independent.

# General descriptions

- Pseudo-Riemannian geometry (as in GR) assumes that our manifold contains curvature (and nothing more).
- This assumption automatically gives us a unique connection: Levi-Civita connection  $\Gamma^{\lambda}_{\mu\nu}$  that is completely defined in terms of a metric  $g_{\mu\nu}$ .
- Curvature  $R^{\lambda}_{\rho\mu\nu}$  and all other geometrical quantities (like Weyl) are NOT independent quantities: The metric tensor fully determines them.
- We aim to construct consistent new theories of gravity with new effects by modifying the geometry.
- By doing that, the metric is no longer the only independent quantity, but now the general affine connection  $\tilde{\Gamma}^{\lambda}_{\mu\nu}$  is also independent.
- In the most general scenario, geometry contains curvature, torsion and nonmetricity. Those geometries are labelled as “Metric-Affine geometries.”

# Definitions and conventions

- The metric tensor  $g_{\mu\nu}$  constitutes a natural isomorphism between the tangent and cotangent spaces defined at any point of the differentiable manifold

$$U_\mu = g_{\mu\nu}U^\nu ,$$

which introduces the notion of the scalar product

$$\mathbf{U} \cdot \mathbf{V} = g_{\mu\nu}U^\mu V^\nu .$$

# Definitions and conventions

- The metric tensor  $g_{\mu\nu}$  constitutes a natural isomorphism between the tangent and cotangent spaces defined at any point of the differentiable manifold

$$U_\mu = g_{\mu\nu}U^\nu ,$$

which introduces the notion of the scalar product

$$\mathbf{U} \cdot \mathbf{V} = g_{\mu\nu}U^\mu V^\nu .$$

- Thus it allows the measurement of infinitesimal distances

$$ds^2 = g_{\mu\nu}dx^\mu dx^\nu ,$$

as well as of vector lengths and angles among them

$$\|\mathbf{U}\| = \sqrt{|g_{\mu\nu}U^\mu U^\nu|}, \quad \cos \alpha = \frac{g_{\mu\nu}m^\mu n^\nu}{\sqrt{|g_{\alpha\beta}m^\alpha m^\beta|}\sqrt{|g_{\gamma\sigma}n^\gamma n^\sigma|}} .$$

# Definitions and conventions

- The affine/linear connection  $\tilde{\Gamma}^\rho{}_{\lambda\mu}$  defines the covariant derivative operator

$$\begin{aligned}\tilde{\nabla}_\mu V^\nu &= \partial_\mu V^\nu + \tilde{\Gamma}^\nu{}_{\lambda\mu} V^\lambda, \\ \tilde{\nabla}_\mu V^\nu &\xrightarrow{GCT} \tilde{\nabla}'_\mu V'^\nu = \Lambda_\mu{}^\lambda \Lambda^\nu{}_\rho \tilde{\nabla}_\lambda V^\rho,\end{aligned}$$

and provides the notion of parallel transport along a curve

$$t^\mu \tilde{\nabla}_\mu V^\nu = 0.$$

# Definitions and conventions

- The affine/linear connection  $\tilde{\Gamma}^\rho_{\lambda\mu}$  defines the covariant derivative operator

$$\begin{aligned}\tilde{\nabla}_\mu V^\nu &= \partial_\mu V^\nu + \tilde{\Gamma}^\nu_{\lambda\mu} V^\lambda, \\ \tilde{\nabla}_\mu V^\nu &\xrightarrow{GCT} \tilde{\nabla}'_\mu V'^\nu = \Lambda_\mu^\lambda \Lambda^\nu_\rho \tilde{\nabla}_\lambda V^\rho,\end{aligned}$$

and provides the notion of parallel transport along a curve

$$t^\mu \tilde{\nabla}_\mu V^\nu = 0.$$

- Commutation rule:

$$[\tilde{\nabla}_\mu, \tilde{\nabla}_\nu] v^\lambda = \tilde{R}^\lambda_{\rho\mu\nu} v^\rho + T^\rho_{\mu\nu} \tilde{\nabla}_\rho v^\lambda.$$

# General descriptions

- In general, to determine the dynamics of those theories one has two independent dynamical quantities:  $(g_{\mu\nu}, \tilde{\Gamma}^{\lambda}_{\mu\nu})$ .

# General descriptions

- In general, to determine the dynamics of those theories one has two independent dynamical quantities:  $(g_{\mu\nu}, \tilde{\Gamma}^{\lambda}_{\mu\nu})$ .
- It is convenient to introduce a tangent space and change those dynamical variables with two other ones:

# General descriptions

- In general, to determine the dynamics of those theories one has two independent dynamical quantities:  $(g_{\mu\nu}, \tilde{\Gamma}^\lambda{}_{\mu\nu})$ .
- It is convenient to introduce a tangent space and change those dynamical variables with two other ones:
  - Tetrads (vierbein)  $e^a{}_\mu$  that are related to a metric as  $g_{\mu\nu} = \eta_{ab} e^a{}_\mu e^b{}_\nu$ , with  $\eta_{ab}$  being the Minkowski metric.

# General descriptions

- In general, to determine the dynamics of those theories one has two independent dynamical quantities:  $(g_{\mu\nu}, \tilde{\Gamma}^{\lambda}_{\mu\nu})$ .
- It is convenient to introduce a tangent space and change those dynamical variables with two other ones:
  - Tetrads (vierbein)  $e^a_{\mu}$  that are related to a metric as  $g_{\mu\nu} = \eta_{ab} e^a_{\mu} e^b_{\nu}$ , with  $\eta_{ab}$  being the Minkowski metric.
  - Spin connection  $\omega^a_{b\mu}$  that are related to the affine connection as  $\omega^a_{b\mu} = e^a_{\lambda} e_b^{\rho} \tilde{\Gamma}^{\lambda}_{\rho\mu} + e^a_{\lambda} \partial_{\mu} e_b^{\lambda}$

# General descriptions

- In general, to determine the dynamics of those theories one has two independent dynamical quantities:  $(g_{\mu\nu}, \tilde{\Gamma}^\lambda{}_{\mu\nu})$ .
- It is convenient to introduce a tangent space and change those dynamical variables with two other ones:
  - Tetrads (vierbein)  $e^a{}_\mu$  that are related to a metric as  $g_{\mu\nu} = \eta_{ab} e^a{}_\mu e^b{}_\nu$ , with  $\eta_{ab}$  being the Minkowski metric.
  - Spin connection  $\omega^a{}_{b\mu}$  that are related to the affine connection as  $\omega^a{}_{b\mu} = e^a{}_\lambda e_b{}^\rho \tilde{\Gamma}^\lambda{}_{\rho\mu} + e^a{}_\lambda \partial_\mu e_b{}^\lambda$
- In these new variables, one can easily define spinors (as in GR) but one of the main advantage is that the curvature form DO NOT depend on the tetrad field (or metric):

$$F^a{}_{b\mu\nu} = \partial_\mu \omega^a{}_{b\nu} - \partial_\nu \omega^a{}_{b\mu} + \omega^a{}_{c\mu} \omega^c{}_{b\nu} - \omega^a{}_{c\nu} \omega^c{}_{b\mu}.$$

# General descriptions

- In general, to determine the dynamics of those theories one has two independent dynamical quantities:  $(g_{\mu\nu}, \tilde{\Gamma}^\lambda{}_{\mu\nu})$ .
- It is convenient to introduce a tangent space and change those dynamical variables with two other ones:
  - Tetrads (vierbein)  $e^a{}_\mu$  that are related to a metric as  $g_{\mu\nu} = \eta_{ab} e^a{}_\mu e^b{}_\nu$ , with  $\eta_{ab}$  being the Minkowski metric.
  - Spin connection  $\omega^a{}_{b\mu}$  that are related to the affine connection as  $\omega^a{}_{b\mu} = e^a{}_\lambda e_b{}^\rho \tilde{\Gamma}^\lambda{}_{\rho\mu} + e^a{}_\lambda \partial_\mu e_b{}^\lambda$
- In these new variables, one can easily define spinors (as in GR) but one of the main advantage is that the curvature form DO NOT depend on the tetrad field (or metric):

$$F^a{}_{b\mu\nu} = \partial_\mu \omega^a{}_{b\nu} - \partial_\nu \omega^a{}_{b\mu} + \omega^a{}_{c\mu} \omega^c{}_{b\nu} - \omega^a{}_{c\nu} \omega^c{}_{b\mu}.$$

- Recall that one can "go back" to the standard curvature by contracting this quantity with tetrads:

$$\tilde{R}^\lambda{}_{\rho\mu\nu} = e_a{}^\lambda e_b{}^\rho F^a{}_{b\mu\nu}$$

# Definitions and conventions

# Definitions and conventions

# Definitions and conventions

- Definition of the curvature tensor:

$$\tilde{R}^{\lambda}{}_{\rho\mu\nu} = \partial_{\mu}\tilde{\Gamma}^{\lambda}{}_{\rho\nu} - \partial_{\nu}\tilde{\Gamma}^{\lambda}{}_{\rho\mu} + \tilde{\Gamma}^{\lambda}{}_{\sigma\mu}\tilde{\Gamma}^{\sigma}{}_{\rho\nu} - \tilde{\Gamma}^{\lambda}{}_{\sigma\nu}\tilde{\Gamma}^{\sigma}{}_{\rho\mu}.$$

# Definitions and conventions

- Definition of the curvature tensor:

$$\tilde{R}^{\lambda}{}_{\rho\mu\nu} = \partial_{\mu}\tilde{\Gamma}^{\lambda}{}_{\rho\nu} - \partial_{\nu}\tilde{\Gamma}^{\lambda}{}_{\rho\mu} + \tilde{\Gamma}^{\lambda}{}_{\sigma\mu}\tilde{\Gamma}^{\sigma}{}_{\rho\nu} - \tilde{\Gamma}^{\lambda}{}_{\sigma\nu}\tilde{\Gamma}^{\sigma}{}_{\rho\mu} .$$

- In particular, it measures the change of vector components on parallel transport along an infinitesimal closed curve:

$$\delta V_{\mu} = \tilde{R}^{\lambda}{}_{\mu\rho\nu} V_{\lambda} ds^{\rho\nu} ,$$

where  $ds^{\rho\nu}$  denotes the surface element spanned by the infinitesimal closed curve.

# Definitions and conventions

- Definition of the curvature tensor:

$$\tilde{R}^{\lambda}{}_{\rho\mu\nu} = \partial_{\mu}\tilde{\Gamma}^{\lambda}{}_{\rho\nu} - \partial_{\nu}\tilde{\Gamma}^{\lambda}{}_{\rho\mu} + \tilde{\Gamma}^{\lambda}{}_{\sigma\mu}\tilde{\Gamma}^{\sigma}{}_{\rho\nu} - \tilde{\Gamma}^{\lambda}{}_{\sigma\nu}\tilde{\Gamma}^{\sigma}{}_{\rho\mu} .$$

- In particular, it measures the change of vector components on parallel transport along an infinitesimal closed curve:

$$\delta V_{\mu} = \tilde{R}^{\lambda}{}_{\mu\rho\nu} V_{\lambda} ds^{\rho\nu} ,$$

where  $ds^{\rho\nu}$  denotes the surface element spanned by the infinitesimal closed curve.

- 96 independent components.

# Definitions and conventions

- Definition of the curvature tensor:

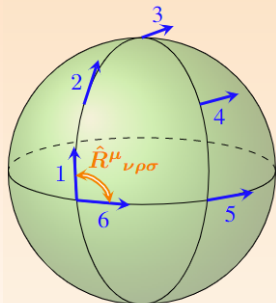
$$\tilde{R}^{\lambda}{}_{\rho\mu\nu} = \partial_{\mu}\tilde{\Gamma}^{\lambda}{}_{\rho\nu} - \partial_{\nu}\tilde{\Gamma}^{\lambda}{}_{\rho\mu} + \tilde{\Gamma}^{\lambda}{}_{\sigma\mu}\tilde{\Gamma}^{\sigma}{}_{\rho\nu} - \tilde{\Gamma}^{\lambda}{}_{\sigma\nu}\tilde{\Gamma}^{\sigma}{}_{\rho\mu}.$$

- In particular, it measures the change of vector components on parallel transport along an infinitesimal closed curve:

$$\delta V_{\mu} = \tilde{R}^{\lambda}{}_{\mu\rho\nu} V_{\lambda} ds^{\rho\nu},$$

where  $ds^{\rho\nu}$  denotes the surface element spanned by the infinitesimal closed curve.

- 96 independent components.



# Definitions and conventions

# Definitions and conventions

# Definitions and conventions

Definition of the torsion tensor:

$$T^\lambda{}_{\mu\nu} = 2\tilde{\Gamma}^\lambda{}_{[\mu\nu]}.$$

# Definitions and conventions

Definition of the torsion tensor:

$$T^{\lambda}{}_{\mu\nu} = 2\tilde{\Gamma}^{\lambda}{}_{[\mu\nu]}.$$

Although the affine connection is not a tensor quantity, its antisymmetric part transforms as a tensor under general coordinate transformations.

Definition of the torsion tensor:

$$T^{\lambda}{}_{\mu\nu} = 2\tilde{\Gamma}^{\lambda}{}_{[\mu\nu]}.$$

Although the affine connection is not a tensor quantity, its antisymmetric part transforms as a tensor under general coordinate transformations.

In particular, it measures the nonclosure of infinitesimal parallelograms:

$$\delta_{U,V} = T^{\rho}{}_{\mu\nu}\delta U^{\mu}\delta V^{\nu}.$$

# Definitions and conventions

Definition of the torsion tensor:

$$T^{\lambda}{}_{\mu\nu} = 2\tilde{\Gamma}^{\lambda}{}_{[\mu\nu]}.$$

Although the affine connection is not a tensor quantity, its antisymmetric part transforms as a tensor under general coordinate transformations.

In particular, it measures the nonclosure of infinitesimal parallelograms:

$$\delta_{U,V} = T^{\rho}{}_{\mu\nu}\delta U^{\mu}\delta V^{\nu}.$$

24 independent components.

# Definitions and conventions

Definition of the torsion tensor:

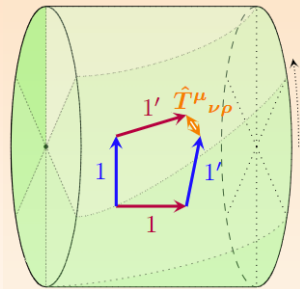
$$T^\lambda{}_{\mu\nu} = 2\tilde{\Gamma}^\lambda{}_{[\mu\nu]}.$$

Although the affine connection is not a tensor quantity, its antisymmetric part transforms as a tensor under general coordinate transformations.

In particular, it measures the nonclosure of infinitesimal parallelograms:

$$\delta_{U,V} = T^\rho{}_{\mu\nu} \delta U^\mu \delta V^\nu.$$

24 independent components.



# Definitions and conventions

# Definitions and conventions

# Definitions and conventions

Definition of the nonmetricity tensor:

$$Q_{\lambda\mu\nu} = \tilde{\nabla}_{\lambda} g_{\mu\nu} .$$

# Definitions and conventions

Definition of the nonmetricity tensor:

$$Q_{\lambda\mu\nu} = \tilde{\nabla}_\lambda g_{\mu\nu} .$$

In particular, it measures the change of lengths and angles under parallel transport:

$$\begin{aligned} V^\lambda \tilde{\nabla}_\lambda (g_{\mu\nu} \hat{m}^\mu \hat{n}^\nu) &= V^\lambda Q_{\lambda\mu\nu} \hat{m}^\mu \hat{n}^\nu \\ &\quad - \frac{1}{2} V^\lambda Q_{\lambda\mu\nu} (\hat{m}^\mu \hat{m}^\nu + \hat{n}^\mu \hat{n}^\nu) \hat{m}^\rho \hat{n}_\rho , \\ V^\lambda \tilde{\nabla}_\lambda \|\mathbf{k}\|^2 &= V^\lambda Q_{\lambda\mu\nu} k^\mu k^\nu . \end{aligned}$$

# Definitions and conventions

Definition of the nonmetricity tensor:

$$Q_{\lambda\mu\nu} = \tilde{\nabla}_{\lambda} g_{\mu\nu} .$$

In particular, it measures the change of lengths and angles under parallel transport:

$$\begin{aligned} V^{\lambda} \tilde{\nabla}_{\lambda} (g_{\mu\nu} \hat{m}^{\mu} \hat{n}^{\nu}) &= V^{\lambda} Q_{\lambda\mu\nu} \hat{m}^{\mu} \hat{n}^{\nu} \\ &- \frac{1}{2} V^{\lambda} Q_{\lambda\mu\nu} (\hat{m}^{\mu} \hat{m}^{\nu} + \hat{n}^{\mu} \hat{n}^{\nu}) \hat{m}^{\rho} \hat{n}_{\rho} , \\ V^{\lambda} \tilde{\nabla}_{\lambda} \|\mathbf{k}\|^2 &= V^{\lambda} Q_{\lambda\mu\nu} k^{\mu} k^{\nu} . \end{aligned}$$

40 independent components.

# Definitions and conventions

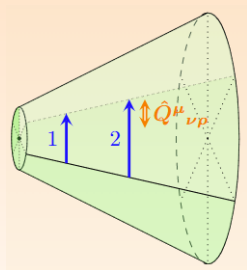
Definition of the nonmetricity tensor:

$$Q_{\lambda\mu\nu} = \tilde{\nabla}_\lambda g_{\mu\nu} .$$

In particular, it measures the change of lengths and angles under parallel transport:

$$\begin{aligned} V^\lambda \tilde{\nabla}_\lambda (g_{\mu\nu} \hat{m}^\mu \hat{n}^\nu) &= V^\lambda Q_{\lambda\mu\nu} \hat{m}^\mu \hat{n}^\nu \\ &- \frac{1}{2} V^\lambda Q_{\lambda\mu\nu} (\hat{m}^\mu \hat{m}^\nu + \hat{n}^\mu \hat{n}^\nu) \hat{m}^\rho \hat{n}_\rho , \\ V^\lambda \tilde{\nabla}_\lambda \|\mathbf{k}\|^2 &= V^\lambda Q_{\lambda\mu\nu} k^\mu k^\nu . \end{aligned}$$

40 independent components.



- In the context of continuum mechanics, the geometric tools of gravity have been used to describe various effects in continuum mechanics.

# Geometry and continuum mechanics

- In the context of continuum mechanics, the geometric tools of gravity have been used to describe various effects in continuum mechanics.
- Deformations can be understood as analogous to take a Minkowski crystal and deform it. They can be associated to change in the microstructure of crystals.

# Geometry and continuum mechanics

- In the context of continuum mechanics, the geometric tools of gravity have been used to describe various effects in continuum mechanics.
- Deformations can be understood as analogous to take a Minkowski crystal and deform it. They can be associated to change in the microstructure of crystals.
- **Curvature:** can be understood as disclination (rotational symmetries are broken)

# Geometry and continuum mechanics

- In the context of continuum mechanics, the geometric tools of gravity have been used to describe various effects in continuum mechanics.
- Deformations can be understood as analogous to take a Minkowski crystal and deform it. They can be associated to change in the microstructure of crystals.
- **Curvature:** can be understood as disclination (rotational symmetries are broken)
- **Torsion:** can be understood as dislocations (translation symmetries are broken) which are crystallographic defects, or irregularities, in the crystal structure.

# Geometry and continuum mechanics

- In the context of continuum mechanics, the geometric tools of gravity have been used to describe various effects in continuum mechanics.
- Deformations can be understood as analogous to take a Minkowski crystal and deform it. They can be associated to change in the microstructure of crystals.
- **Curvature:** can be understood as disclination (rotational symmetries are broken)
- **Torsion:** can be understood as dislocations (translation symmetries are broken) which are crystallographic defects, or irregularities, in the crystal structure.
- **Nonmetricity:** can be understood as crystalline structure with point defects (vacancies/interstitials)

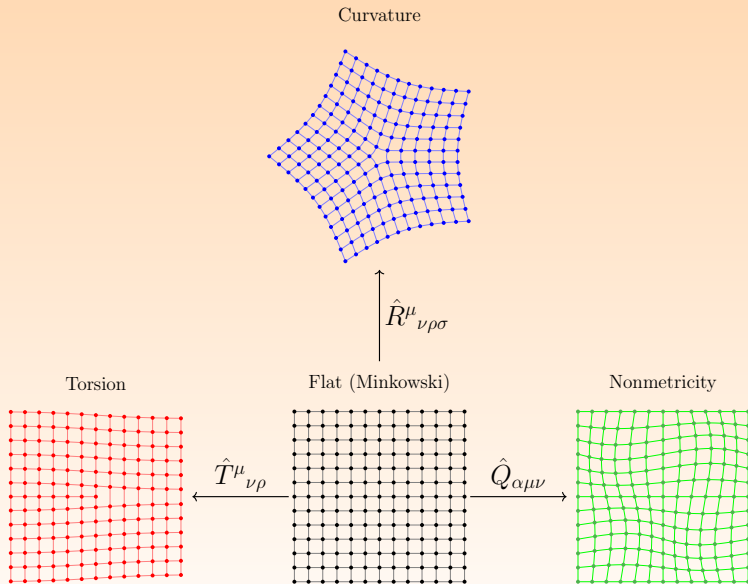


Figure: Crystalline structure and its analogy with curvature, torsion and nonmetricity

# Matter sector: source of torsion/nonmetricity

- We have energy-momentum tensor and an additional matter sector: hypermomentum density that sources Torsion/Nonmetricity.

# Matter sector: source of torsion/nonmetricity

- We have energy-momentum tensor and an additional matter sector: hypermomentum density that sources Torsion/Nonmetricity.
- This new quantity can be split into three pieces:

$$\Delta_{\mu\nu\lambda} = {}^{(s)}\Delta_{[\mu\nu]\lambda} + \frac{1}{4}g_{\mu\nu}{}^{(d)}\Delta_{\lambda} + {}^{(sh)}\mathbb{X}_{(\mu\nu)\lambda}.$$

Here, the first part is related to intrinsic spin (which is the source of torsion), the second part is related to intrinsic dilations (which is the source of the trace part of nonmetricity) with  ${}^{(d)}\Delta_{\mu} = \Delta^{\nu}{}_{\nu\mu}$ , and the last part is related to intrinsic shears (which provide a source for the traceless part of nonmetricity).

# Matter sector: source of torsion/nonmetricity

- We have energy-momentum tensor and an additional matter sector: hypermomentum density that sources Torsion/Nonmetricity.
- This new quantity can be split into three pieces:

$$\Delta_{\mu\nu\lambda} = {}^{(s)}\Delta_{[\mu\nu]\lambda} + \frac{1}{4}g_{\mu\nu}{}^{(d)}\Delta_{\lambda} + {}^{(sh)}\mathbb{X}_{(\mu\nu)\lambda}.$$

Here, the first part is related to intrinsic spin (which is the source of torsion), the second part is related to intrinsic dilations (which is the source of the trace part of nonmetricity) with  ${}^{(d)}\Delta_{\mu} = \Delta^{\nu}{}_{\nu\mu}$ , and the last part is related to intrinsic shears (which provide a source for the traceless part of nonmetricity).

- Remember that they are INTRINSIC properties of the geometry. Intrinsic spin  $\neq$  macroscopic spin (for example Kerr angular momentum)

# Example: Dirac equation in the presence of torsion

- Covariant derivative of a Dirac spinor and its adjoint

$$\tilde{\nabla}_\mu \Psi = \partial_\mu \Psi - \frac{1}{8} \omega^{ab}{}_\mu [\gamma_a, \gamma_b] \Psi ,$$

$$\tilde{\nabla}_\mu \bar{\Psi} = \partial_\mu \bar{\Psi} + \frac{1}{8} \omega^{ab}{}_\mu \bar{\Psi} [\gamma_a, \gamma_b] .$$

# Example: Dirac equation in the presence of torsion

- Covariant derivative of a Dirac spinor and its adjoint

$$\tilde{\nabla}_\mu \Psi = \partial_\mu \Psi - \frac{1}{8} \omega^{ab}{}_\mu [\gamma_a, \gamma_b] \Psi ,$$

$$\tilde{\nabla}_\mu \bar{\Psi} = \partial_\mu \bar{\Psi} + \frac{1}{8} \omega^{ab}{}_\mu \bar{\Psi} [\gamma_a, \gamma_b] .$$

- The Dirac Lagrangian provides the dynamics of 1/2 spin fields under minimal coupling

$$\tilde{\mathcal{L}}_{\text{Dirac}} = \frac{i}{2} \left( \bar{\Psi} \gamma^\mu \tilde{\nabla}_\mu \Psi - \tilde{\nabla}_\mu \bar{\Psi} \gamma^\mu \Psi - 2im \bar{\Psi} \Psi \right) .$$

# Example: Dirac equation in the presence of torsion

- Covariant derivative of a Dirac spinor and its adjoint

$$\tilde{\nabla}_\mu \Psi = \partial_\mu \Psi - \frac{1}{8} \omega^{ab}{}_\mu [\gamma_a, \gamma_b] \Psi ,$$

$$\tilde{\nabla}_\mu \bar{\Psi} = \partial_\mu \bar{\Psi} + \frac{1}{8} \omega^{ab}{}_\mu \bar{\Psi} [\gamma_a, \gamma_b] .$$

- The Dirac Lagrangian provides the dynamics of 1/2 spin fields under minimal coupling

$$\tilde{\mathcal{L}}_{\text{Dirac}} = \frac{i}{2} \left( \bar{\Psi} \gamma^\mu \tilde{\nabla}_\mu \Psi - \tilde{\nabla}_\mu \bar{\Psi} \gamma^\mu \Psi - 2im \bar{\Psi} \Psi \right) .$$

- In the framework of post-Riemannian geometry

$$\tilde{\mathcal{L}}_{\text{Dirac}} = \mathcal{L}_{\text{Dirac}} - \frac{i}{16} e^{a\mu} e^b{}_\lambda e^{c\rho} K^\lambda{}_{\rho\mu} \bar{\Psi} \{ \gamma_a, [\gamma_b, \gamma_c] \} \Psi .$$

# Example: Dirac equation in the presence of torsion

- Covariant derivative of a Dirac spinor and its adjoint

$$\tilde{\nabla}_\mu \Psi = \partial_\mu \Psi - \frac{1}{8} \omega^{ab}{}_\mu [\gamma_a, \gamma_b] \Psi ,$$

$$\tilde{\nabla}_\mu \bar{\Psi} = \partial_\mu \bar{\Psi} + \frac{1}{8} \omega^{ab}{}_\mu \bar{\Psi} [\gamma_a, \gamma_b] .$$

- The Dirac Lagrangian provides the dynamics of 1/2 spin fields under minimal coupling

$$\tilde{\mathcal{L}}_{\text{Dirac}} = \frac{i}{2} \left( \bar{\Psi} \gamma^\mu \tilde{\nabla}_\mu \Psi - \tilde{\nabla}_\mu \bar{\Psi} \gamma^\mu \Psi - 2im \bar{\Psi} \Psi \right) .$$

- In the framework of post-Riemannian geometry

$$\tilde{\mathcal{L}}_{\text{Dirac}} = \mathcal{L}_{\text{Dirac}} - \frac{i}{16} e^{a\mu} e^b{}_\lambda e^{c\rho} K^\lambda{}_{\rho\mu} \bar{\Psi} \{ \gamma_a, [\gamma_b, \gamma_c] \} \Psi .$$

- Accordingly, only the axial mode of torsion interacts with 1/2 fields under minimal coupling

$$\tilde{\mathcal{L}}_{\text{Dirac}} = \mathcal{L}_{\text{Dirac}} - \frac{1}{8} \varepsilon^{\lambda\rho\mu\nu} T_{\lambda\rho\mu} \bar{\Psi} \gamma^5 \gamma_\nu \Psi .$$

# Symmetries and identities of the curvature tensor

- Skew symmetry of the last pair of indices of the curvature tensor:

$$\tilde{R}_{\rho\sigma(\mu\nu)} = 0.$$

# Symmetries and identities of the curvature tensor

- Skew symmetry of the last pair of indices of the curvature tensor:

$$\tilde{R}_{\rho\sigma(\mu\nu)} = 0.$$

- Bianchi identities:

$$\begin{aligned}\tilde{R}^{\lambda}{}_{[\mu\nu\rho]} &= \tilde{\nabla}_{[\mu} T^{\lambda}{}_{\rho\nu]} + T^{\sigma}{}_{[\mu\rho} T^{\lambda}{}_{\nu]\sigma}, \\ \tilde{\nabla}_{[\sigma} \tilde{R}^{\lambda}{}_{\rho|\mu\nu]} &= T^{\omega}{}_{[\sigma\mu} \tilde{R}^{\lambda}{}_{\rho\omega|\nu]}, \\ \tilde{R}^{(\lambda\rho)}{}_{\mu\nu} &= \tilde{\nabla}_{[\nu} Q_{\mu]}{}^{\lambda\rho} + \frac{1}{2} T^{\sigma}{}_{\mu\nu} Q_{\sigma}{}^{\lambda\rho}.\end{aligned}$$

# Symmetries and identities of the curvature tensor

- Skew symmetry of the last pair of indices of the curvature tensor:

$$\tilde{R}_{\rho\sigma(\mu\nu)} = 0.$$

- Bianchi identities:

$$\begin{aligned}\tilde{R}^{\lambda}{}_{[\mu\nu\rho]} &= \tilde{\nabla}_{[\mu} T^{\lambda}{}_{\rho\nu]} + T^{\sigma}{}_{[\mu\rho} T^{\lambda}{}_{\nu]\sigma}, \\ \tilde{\nabla}_{[\sigma} \tilde{R}^{\lambda}{}_{\rho|\mu\nu]} &= T^{\omega}{}_{[\sigma\mu} \tilde{R}^{\lambda}{}_{\rho\omega|\nu]}, \\ \tilde{R}^{(\lambda\rho)}{}_{\mu\nu} &= \tilde{\nabla}_{[\nu} Q_{\mu]}{}^{\lambda\rho} + \frac{1}{2} T^{\sigma}{}_{\mu\nu} Q_{\sigma}{}^{\lambda\rho}.\end{aligned}$$

- Three independent rank-2 tensors defined from the first contractions of the curvature tensor:

$$\tilde{R}_{\mu\nu} = \tilde{R}^{\lambda}{}_{\mu\lambda\nu}, \quad \hat{R}_{\mu\nu} = \tilde{R}_{\mu}{}^{\lambda}{}_{\nu\lambda}, \quad \tilde{R}^{\lambda}{}_{\lambda\mu\nu} = \nabla_{[\nu} Q_{\mu]}{}^{\lambda}{}_{\lambda}.$$

# Symmetries and identities of the curvature tensor

- Skew symmetry of the last pair of indices of the curvature tensor:

$$\tilde{R}_{\rho\sigma(\mu\nu)} = 0.$$

- Bianchi identities:

$$\begin{aligned}\tilde{R}^{\lambda}{}_{[\mu\nu\rho]} &= \tilde{\nabla}_{[\mu} T^{\lambda}{}_{\rho\nu]} + T^{\sigma}{}_{[\mu\rho} T^{\lambda}{}_{\nu]\sigma}, \\ \tilde{\nabla}_{[\sigma} \tilde{R}^{\lambda}{}_{\rho|\mu\nu]} &= T^{\omega}{}_{[\sigma\mu} \tilde{R}^{\lambda}{}_{\rho\omega|\nu]}, \\ \tilde{R}^{(\lambda\rho)}{}_{\mu\nu} &= \tilde{\nabla}_{[\nu} Q_{\mu]}{}^{\lambda\rho} + \frac{1}{2} T^{\sigma}{}_{\mu\nu} Q_{\sigma}{}^{\lambda\rho}.\end{aligned}$$

- Three independent rank-2 tensors defined from the first contractions of the curvature tensor:

$$\tilde{R}_{\mu\nu} = \tilde{R}^{\lambda}{}_{\mu\lambda\nu}, \quad \hat{R}_{\mu\nu} = \tilde{R}_{\mu}{}^{\lambda}{}_{\nu\lambda}, \quad \tilde{R}^{\lambda}{}_{\lambda\mu\nu} = \nabla_{[\nu} Q_{\mu]}{}^{\lambda}{}_{\lambda}.$$

- Unique scalar and pseudoscalar curvatures:

$$\tilde{R} = g^{\mu\nu} \tilde{R}_{\mu\nu}, \quad * \tilde{R} = \varepsilon^{\lambda\rho\mu\nu} \tilde{R}_{\lambda\rho\mu\nu}.$$

# Post-Riemannian decomposition

- It is useful to separate the connection as

$$\tilde{\Gamma}^{\lambda}{}_{\mu\nu} = \Gamma^{\lambda}{}_{\mu\nu} + N^{\lambda}{}_{\mu\nu},$$

with

$$N^{\lambda}{}_{\mu\nu} = K^{\lambda}{}_{\mu\nu} + L^{\lambda}{}_{\mu\nu},$$

where the contortion  $K^{\lambda}{}_{\mu\nu}$  and disformation tensors  $L^{\lambda}{}_{\mu\nu}$  are

$$K^{\lambda}{}_{\mu\nu} = \frac{1}{2} \left( T^{\lambda}{}_{\mu\nu} - T_{\mu}{}^{\lambda}{}_{\nu} - T_{\nu}{}^{\lambda}{}_{\mu} \right),$$

$$L^{\lambda}{}_{\mu\nu} = \frac{1}{2} \left( Q^{\lambda}{}_{\mu\nu} - Q_{\mu}{}^{\lambda}{}_{\nu} - Q_{\nu}{}^{\lambda}{}_{\mu} \right).$$

# Post-Riemannian decomposition

- It is useful to separate the connection as

$$\tilde{\Gamma}^\lambda{}_{\mu\nu} = \Gamma^\lambda{}_{\mu\nu} + N^\lambda{}_{\mu\nu},$$

with

$$N^\lambda{}_{\mu\nu} = K^\lambda{}_{\mu\nu} + L^\lambda{}_{\mu\nu},$$

where the contortion  $K^\lambda{}_{\mu\nu}$  and disformation tensors  $L^\lambda{}_{\mu\nu}$  are

$$K^\lambda{}_{\mu\nu} = \frac{1}{2} \left( T^\lambda{}_{\mu\nu} - T_\mu{}^\lambda{}_\nu - T_\nu{}^\lambda{}_\mu \right),$$

$$L^\lambda{}_{\mu\nu} = \frac{1}{2} \left( Q^\lambda{}_{\mu\nu} - Q_\mu{}^\lambda{}_\nu - Q_\nu{}^\lambda{}_\mu \right).$$

- General decomposition of the the curvature tensor:

$$\tilde{R}^\lambda{}_{\rho\mu\nu} = R^\lambda{}_{\rho\mu\nu} + 2\nabla_{[\mu} N^\lambda{}_{\rho|\nu]} + 2N^\lambda{}_{\sigma[\mu} N^\sigma{}_{\rho|\nu]}.$$

# Overview of the Talk

- 1 General descriptions of theories with torsion and nonmetricity
- 2 The gauge approach of gravity: Poincare gauge theory
- 3 Fallacies of torsion
- 4 Poincare gauge gravity: Stability and theory
- 5 Black holes
  - Spherically symmetric black holes
  - Axially symmetric black holes
- 6 Cosmology

# Dynamics and action

- One can write down an action of the form

$$S = \int d^4x \sqrt{-g} \left[ \mathcal{L}_m - \frac{1}{2\kappa^2} \mathcal{L}_g(\tilde{\mathcal{R}}, \mathcal{T}) \right].$$

with  $\kappa^2 = 8\pi G$ .

# Dynamics and action

- One can write down an action of the form

$$S = \int d^4x \sqrt{-g} \left[ \mathcal{L}_m - \frac{1}{2\kappa^2} \mathcal{L}_g(\tilde{\mathcal{R}}, \mathcal{T}) \right].$$

with  $\kappa^2 = 8\pi G$ .

- Correspondence between geometry and matter:

$$\frac{1}{\sqrt{-g}} \frac{\delta(\mathcal{L}_g \sqrt{-g})}{\delta e^a{}_\nu} = 2\kappa^2 \theta_a{}^\nu,$$
$$\frac{1}{\sqrt{-g}} \frac{\delta(\mathcal{L}_g \sqrt{-g})}{\delta \omega^a{}_{b\nu}} = 2\kappa^2 \Delta_a{}^{b\nu},$$

where we have two matter sources:

$$\theta_\mu{}^\nu = \frac{e^a{}_\mu}{\sqrt{-g}} \frac{\delta(\sqrt{-g} \mathcal{L}_m)}{\delta e^a{}_\nu},$$
$$\Delta^{\lambda\mu\nu} = \frac{e^{a\lambda} e_b{}^\mu}{\sqrt{-g}} \frac{\delta(\sqrt{-g} \mathcal{L}_m)}{\delta \omega^a{}_{b\nu}}.$$

# Conservation equation

- $\theta_a{}^\nu$  is the canonical energy-momentum tensor that can be related to the energy-momentum tensor as

$$\Theta^\mu{}_\lambda = T^\mu{}_\lambda + \frac{1}{2\sqrt{-g}} \left[ \tilde{\nabla}_\nu (\sqrt{-g} \Delta_\lambda{}^{\mu\nu}) - 2\sqrt{-g} T_\nu \Delta_\lambda{}^{\mu\nu} \right].$$

# Conservation equation

- $\theta_a{}^\nu$  is the canonical energy-momentum tensor that can be related to the energy-momentum tensor as

$$\Theta^\mu{}_\lambda = T^\mu{}_\lambda + \frac{1}{2\sqrt{-g}} \left[ \tilde{\nabla}_\nu (\sqrt{-g} \Delta_\lambda{}^{\mu\nu}) - 2\sqrt{-g} T_\nu \Delta_\lambda{}^{\mu\nu} \right].$$

- By imposing that the matter sector respects diffeomorphism invariance, we arrive at the following generalised conservation equation:

$$\begin{aligned} \nabla_\mu T^\mu{}_\alpha - \frac{1}{2} \Delta^{\lambda\mu\nu} \tilde{R}_{\lambda\mu\nu\alpha} + \frac{1}{2} \tilde{\nabla}_\mu \tilde{\nabla}_\nu \Delta_\alpha{}^{\mu\nu} \\ + T_{\mu\alpha}{}^\lambda \tilde{\nabla}_\nu \Delta_\lambda{}^{\mu\nu} = 0. \end{aligned}$$

# Conservation equation

- $\theta_a{}^\nu$  is the canonical energy-momentum tensor that can be related to the energy-momentum tensor as

$$\Theta^\mu{}_\lambda = T^\mu{}_\lambda + \frac{1}{2\sqrt{-g}} \left[ \tilde{\nabla}_\nu (\sqrt{-g} \Delta_\lambda{}^{\mu\nu}) - 2\sqrt{-g} T_\nu \Delta_\lambda{}^{\mu\nu} \right].$$

- By imposing that the matter sector respects diffeomorphism invariance, we arrive at the following generalised conservation equation:

$$\begin{aligned} \nabla_\mu T^\mu{}_\alpha - \frac{1}{2} \Delta^{\lambda\mu\nu} \tilde{R}_{\lambda\mu\nu\alpha} + \frac{1}{2} \tilde{\nabla}_\mu \tilde{\nabla}_\nu \Delta_\alpha{}^{\mu\nu} \\ + T_{\mu\alpha}{}^\lambda \tilde{\nabla}_\nu \Delta_\lambda{}^{\mu\nu} = 0. \end{aligned}$$

- Obviously, if there is no hypermomentum, we find the standard energy-momentum conservation  $\nabla_\mu T^\mu{}_\alpha = 0$ .

# Poincaré gauge theory

- $ISO(1, 3) = T^4 \times SO(1, 3)$  gauge connection<sup>1</sup>:

$$A_\mu = e^a{}_\mu P_a + \omega^a{}_{b\mu} J_a{}^b,$$

$$g_{\mu\nu} = e^a{}_\mu e^b{}_\nu \eta_{ab},$$

where

$$\omega^a{}_{b\mu} = e^a{}_\lambda e_b{}^\rho \tilde{\Gamma}^\lambda{}_{\rho\mu} + e^a{}_\lambda \partial_\mu e_b{}^\lambda.$$

---

<sup>1</sup>F. W. Hehl, P. von der Heyde, G. D. Kerlick and J. M. Nester, Rev. Mod. Phys. **48**, 393 (1976).

# Poincaré gauge theory

- $ISO(1, 3) = T^4 \rtimes SO(1, 3)$  gauge connection<sup>1</sup>:

$$A_\mu = e^a{}_\mu P_a + \omega^a{}_{b\mu} J_a{}^b,$$
$$g_{\mu\nu} = e^a{}_\mu e^b{}_\nu \eta_{ab},$$

where

$$\omega^a{}_{b\mu} = e^a{}_\lambda e_b{}^\rho \tilde{\Gamma}^\lambda{}_{\rho\mu} + e^a{}_\lambda \partial_\mu e_b{}^\lambda.$$

- Generators of the Poincaré group  $ISO(1, 3)$ :

$$[P_a, P_b] = 0,$$
$$[P_a, J_{bc}] = i \eta_{a[b} P_{c]},$$
$$[J_{ab}, J_{cd}] = \frac{i}{2} (\eta_{ad} J_{bc} + \eta_{cb} J_{ad} - \eta_{db} J_{ac} - \eta_{ac} J_{bd}).$$

---

<sup>1</sup>F. W. Hehl, P. von der Heyde, G. D. Kerlick and J. M. Nester, Rev. Mod. Phys. **48**, 393 (1976).

# Quadratic Poincaré gauge theory

- $ISO(1, 3)$  translational and rotational field strength tensors:

$$F_{\mu\nu} = F^a{}_{\mu\nu} P_a + F^a{}_{b\mu\nu} J_a{}^b,$$

where

$$F^a{}_{\mu\nu} = \partial_\mu e^a{}_\nu - \partial_\nu e^a{}_\mu + \omega^a{}_{b\mu} e^b{}_\nu - \omega^a{}_{b\nu} e^b{}_\mu,$$
$$F^a{}_{b\mu\nu} = \partial_\mu \omega^a{}_{b\nu} - \partial_\nu \omega^a{}_{b\mu} + \omega^a{}_{c\mu} \omega^c{}_{b\nu} - \omega^a{}_{c\nu} \omega^c{}_{b\mu}.$$

# Quadratic Poincaré gauge theory

- $ISO(1, 3)$  translational and rotational field strength tensors:

$$F_{\mu\nu} = F^a{}_{\mu\nu} P_a + F^a{}_{b\mu\nu} J_a{}^b,$$

where

$$F^a{}_{\mu\nu} = \partial_\mu e^a{}_\nu - \partial_\nu e^a{}_\mu + \omega^a{}_{b\mu} e^b{}_\nu - \omega^a{}_{b\nu} e^b{}_\mu,$$
$$F^a{}_{b\mu\nu} = \partial_\mu \omega^a{}_{b\nu} - \partial_\nu \omega^a{}_{b\mu} + \omega^a{}_{c\mu} \omega^c{}_{b\nu} - \omega^a{}_{c\nu} \omega^c{}_{b\mu}.$$

- Recall the correspondence with the torsion and curvature tensors:

$$F^a{}_{\mu\nu} = e^a{}_\lambda T^\lambda{}_{\nu\mu},$$
$$F^a{}_{b\mu\nu} = e^a{}_\lambda e_b{}^\rho \tilde{R}^\lambda{}_{\rho\mu\nu}.$$

# Overview of the Talk

- 1 General descriptions of theories with torsion and nonmetricity
- 2 The gauge approach of gravity: Poincare gauge theory
- 3 Fallacies of torsion**
- 4 Poincare gauge gravity: Stability and theory
- 5 Black holes
  - Spherically symmetric black holes
  - Axially symmetric black holes
- 6 Cosmology

# Fallacies about Torsion 1

(book "Gauge Theories of Gravitation", M. Blagojevic and F.W. Hehl)

- Carroll<sup>2</sup> argues on p. 190 of his book said:

---

<sup>2</sup>S. M. Carroll, "Spacetime and Geometry: An Introduction to General Relativity,"

# Fallacies about Torsion 1

(book "Gauge Theories of Gravitation", M. Blagojevic and F.W. Hehl)

- Carroll<sup>2</sup> argues on p. 190 of his book said:

## Fallacy 1: Torsion not distinguished from other tensor fields

“We could drop the demand that the connection be torsion-free, in which case the torsion tensor could lead to additional propagating degrees of freedom. The basic reason why such theories do not receive much attention is simply because the torsion is itself a tensor; there is nothing to distinguish it from other, non-gravitational tensor fields. Thus, we do not really lose any generality by considering theories of torsion-free connections (which lead to GR) plus any number of tensor fields, which we can name what we like. Similar considerations apply when we consider dropping the requirement of metric compatibility—any connection can be written as a metric-compatible connection plus a tensorial correction, so any such theory is equivalent to GR plus extra tensor fields, which wouldn't really deserve to be called an “alternative to general relativity”

<sup>2</sup>S. M. Carroll, “Spacetime and Geometry: An Introduction to General Relativity,”

- This opinion is often expressed by particle physicists who have a somewhat relaxed relation towards differential geometry.

# Fallacies about Torsion 1

(book "Gauge Theories of Gravitation", M. Blagojevic and F.W. Hehl)

- This opinion is often expressed by particle physicists who have a somewhat relaxed relation towards differential geometry.
- The torsion tensor is not any tensor, but a particular tensor related to the translation group.

# Fallacies about Torsion 1

(book "Gauge Theories of Gravitation", M. Blagojevic and F.W. Hehl)

- This opinion is often expressed by particle physicists who have a somewhat relaxed relation towards differential geometry.
- The torsion tensor is not any tensor, but a particular tensor related to the translation group.
- A torsion tensor cracks infinitesimal parallelograms. A parallelogram is deeply related to the geometry of a manifold carrying a linear connection.

# Fallacies about Torsion 1

(book "Gauge Theories of Gravitation", M. Blagojevic and F.W. Hehl)

- This opinion is often expressed by particle physicists who have a somewhat relaxed relation towards differential geometry.
- The torsion tensor is not any tensor, but a particular tensor related to the translation group.
- A torsion tensor cracks infinitesimal parallelograms. A parallelogram is deeply related to the geometry of a manifold carrying a linear connection.
- The closure failure of a parallelogram can only be created by a distinctive geometrical quantity, namely the torsion tensor, and not by any other tensor.

# Fallacies about Torsion 1

(book "Gauge Theories of Gravitation", M. Blagojevic and F.W. Hehl)

- This opinion is often expressed by particle physicists who have a somewhat relaxed relation towards differential geometry.
- The torsion tensor is not any tensor, but a particular tensor related to the translation group.
- A torsion tensor cracks infinitesimal parallelograms. A parallelogram is deeply related to the geometry of a manifold carrying a linear connection.
- The closure failure of a parallelogram can only be created by a distinctive geometrical quantity, namely the torsion tensor, and not by any other tensor.
- Moreover, torsion affects the Bianchi identities

### Is there any physical principle . . . ?

Weinberg claimed "...Sorry, I still don't get it (on the possibility of torsion). Is there any physical principle, such as a principle of invariance, that would require the Christoffel symbol to be accompanied by some specific additional tensor? Or that would forbid it? And if there is such a principle, does it have any other testable consequences?"

### Is there any physical principle . . . ?

Weinberg claimed "...Sorry, I still don't get it (on the possibility of torsion). Is there any physical principle, such as a principle of invariance, that would require the Christoffel symbol to be accompanied by some specific additional tensor? Or that would forbid it? And if there is such a principle, does it have any other testable consequences?"

- The physical principle Weinberg is looking for is translational gauge invariance.

### Is there any physical principle . . . ?

Weinberg claimed "...Sorry, I still don't get it (on the possibility of torsion). Is there any physical principle, such as a principle of invariance, that would require the Christoffel symbol to be accompanied by some specific additional tensor? Or that would forbid it? And if there is such a principle, does it have any other testable consequences?"

- The physical principle Weinberg is looking for is translational gauge invariance.
- The testable consequences are related to the new spin-spin contact interaction and to the precession of elementary particle spins in torsion fields.

## Gravity Probe B and torsion

Torsion can be measured (and constraint a lot) by means of the Gravity Probe B experiment

## Gravity Probe B and torsion

Torsion can be measured (and constraint a lot) by means of the Gravity Probe B experiment

- This is incorrect since the sensitive pieces of this gyroscope experiment, the rotating quartz balls, do not carry uncompensated elementary particle spin

## Gravity Probe B and torsion

Torsion can be measured (and constraint a lot) by means of the Gravity Probe B experiment

- This is incorrect since the sensitive pieces of this gyroscope experiment, the rotating quartz balls, do not carry uncompensated elementary particle spin
- If the balls were made of polarized elementary particle spins, that is, if one had a nuclear gyroscope, as they were constructed for inertial platforms, then the gyroscope would be sensitive to torsion.

## Gravity Probe B and torsion

Torsion can be measured (and constraint a lot) by means of the Gravity Probe B experiment

- This is incorrect since the sensitive pieces of this gyroscope experiment, the rotating quartz balls, do not carry uncompensated elementary particle spin
- If the balls were made of polarized elementary particle spins, that is, if one had a nuclear gyroscope, as they were constructed for inertial platforms, then the gyroscope would be sensitive to torsion.
- Then, it turns out that measuring torsion requires elementary spin, there is no other way. Orbital angular momentum is not a substitute for spin.

## Gravity Probe B and torsion

Torsion can be measured (and constraint a lot) by means of the Gravity Probe B experiment

- This is incorrect since the sensitive pieces of this gyroscope experiment, the rotating quartz balls, do not carry uncompensated elementary particle spin
- If the balls were made of polarized elementary particle spins, that is, if one had a nuclear gyroscope, as they were constructed for inertial platforms, then the gyroscope would be sensitive to torsion.
- Then, it turns out that measuring torsion requires elementary spin, there is no other way. Orbital angular momentum is not a substitute for spin.
- Would you use an electrically and magnetically neutral test particle for tracing possible electromagnetic fields?

## Gravity Probe B and torsion

Torsion can be measured (and constraint a lot) by means of the Gravity Probe B experiment

- This is incorrect since the sensitive pieces of this gyroscope experiment, the rotating quartz balls, do not carry uncompensated elementary particle spin
- If the balls were made of polarized elementary particle spins, that is, if one had a nuclear gyroscope, as they were constructed for inertial platforms, then the gyroscope would be sensitive to torsion.
- Then, it turns out that measuring torsion requires elementary spin, there is no other way. Orbital angular momentum is not a substitute for spin.
- Would you use an electrically and magnetically neutral test particle for tracing possible electromagnetic fields?
- By the same token: Would you use a macroscopically rotating quartz ball of Gravity Probe B for tracing a possible torsion field?

# Overview of the Talk

- 1 General descriptions of theories with torsion and nonmetricity
- 2 The gauge approach of gravity: Poincare gauge theory
- 3 Fallacies of torsion
- 4 Poincare gauge gravity: Stability and theory**
- 5 Black holes
  - Spherically symmetric black holes
  - Axially symmetric black holes
- 6 Cosmology

# Quadratic Poincaré gauge theory - ghost issue

- Convenient to decompose torsion as

$$T^\lambda{}_{\mu\nu} = \frac{1}{3} (\delta^\lambda{}_\nu T_\mu - \delta^\lambda{}_\mu T_\nu) + \frac{1}{6} \varepsilon^\lambda{}_{\rho\mu\nu} S^\rho + t^\lambda{}_{\mu\nu}.$$

using

# Quadratic Poincaré gauge theory - ghost issue

- Convenient to decompose torsion as

$$T^\lambda{}_{\mu\nu} = \frac{1}{3} (\delta^\lambda{}_\nu T_\mu - \delta^\lambda{}_\mu T_\nu) + \frac{1}{6} \varepsilon^\lambda{}_{\rho\mu\nu} S^\rho + t^\lambda{}_{\mu\nu}.$$

using

- Vector part  $T_\mu = T^\lambda{}_{\mu\lambda}$ ,

# Quadratic Poincaré gauge theory - ghost issue

- Convenient to decompose torsion as

$$T^\lambda{}_{\mu\nu} = \frac{1}{3} (\delta^\lambda{}_\nu T_\mu - \delta^\lambda{}_\mu T_\nu) + \frac{1}{6} \varepsilon^\lambda{}_{\rho\mu\nu} S^\rho + t^\lambda{}_{\mu\nu}.$$

using

- Vector part  $T_\mu = T^\lambda{}_{\mu\lambda}$ ,
- Axial vector part  $S_\mu = \varepsilon_{\mu\nu\rho\sigma} T^{\nu\sigma\rho}$ ,

# Quadratic Poincaré gauge theory - ghost issue

- Convenient to decompose torsion as

$$T^\lambda{}_{\mu\nu} = \frac{1}{3} (\delta^\lambda{}_\nu T_\mu - \delta^\lambda{}_\mu T_\nu) + \frac{1}{6} \varepsilon^\lambda{}_{\rho\mu\nu} S^\rho + t^\lambda{}_{\mu\nu}.$$

using

- Vector part  $T_\mu = T^\lambda{}_{\mu\lambda}$ ,
- Axial vector part  $S_\mu = \varepsilon_{\mu\nu\rho\sigma} T^{\nu\sigma\rho}$ ,
- Tensor part  $t^\lambda{}_{\mu\nu} = T^\lambda{}_{\mu\nu} - \frac{1}{3} (\delta^\lambda{}_\nu T_\mu - \delta^\lambda{}_\mu T_\nu) - \frac{1}{6} \varepsilon^\lambda{}_{\rho\mu\nu} S^\rho$ .

# Quadratic Poincaré gauge theory - ghost issue

- Convenient to decompose torsion as

$$T^\lambda{}_{\mu\nu} = \frac{1}{3} (\delta^\lambda{}_\nu T_\mu - \delta^\lambda{}_\mu T_\nu) + \frac{1}{6} \varepsilon^\lambda{}_{\rho\mu\nu} S^\rho + t^\lambda{}_{\mu\nu}.$$

using

- Vector part  $T_\mu = T^\lambda{}_{\mu\lambda}$ ,
  - Axial vector part  $S_\mu = \varepsilon_{\mu\nu\rho\sigma} T^{\nu\sigma\rho}$ ,
  - Tensor part  $t^\lambda{}_{\mu\nu} = T^\lambda{}_{\mu\nu} - \frac{1}{3} (\delta^\lambda{}_\nu T_\mu - \delta^\lambda{}_\mu T_\nu) - \frac{1}{6} \varepsilon^\lambda{}_{\rho\mu\nu} S^\rho$ .
- The most general class of quadratic Poincaré gauge models that are reduced to General Relativity in the absence of torsion is:

$$S_g = \frac{1}{16\pi} \int \left[ -R + c_2 \tilde{R}_{\lambda\rho\mu\nu} \tilde{R}^{\lambda\mu\rho\nu} - \frac{1}{2} (2c_1 + c_2) \tilde{R}_{\lambda\rho\mu\nu} \tilde{R}^{\mu\nu\lambda\rho} + c_1 \tilde{R}_{\lambda\rho\mu\nu} \tilde{R}^{\lambda\rho\mu\nu} \right. \\ \left. + d_1 \tilde{R}_{\mu\nu} (\tilde{R}^{\mu\nu} - \tilde{R}^{\nu\mu}) + \frac{1}{2} (m_T^2 T_\mu T^\mu + m_S^2 S_\mu S^\mu + m_t^2 t_{\lambda\mu\nu} t^{\lambda\mu\nu}) \right] \sqrt{-g} d^4x.$$

# Quadratic Poincaré gauge theory - ghost issue

- Convenient to decompose torsion as

$$T^\lambda{}_{\mu\nu} = \frac{1}{3} (\delta^\lambda{}_\nu T_\mu - \delta^\lambda{}_\mu T_\nu) + \frac{1}{6} \varepsilon^\lambda{}_{\rho\mu\nu} S^\rho + t^\lambda{}_{\mu\nu}.$$

using

- Vector part  $T_\mu = T^\lambda{}_{\mu\lambda}$ ,
  - Axial vector part  $S_\mu = \varepsilon_{\mu\nu\rho\sigma} T^{\nu\sigma\rho}$ ,
  - Tensor part  $t^\lambda{}_{\mu\nu} = T^\lambda{}_{\mu\nu} - \frac{1}{3} (\delta^\lambda{}_\nu T_\mu - \delta^\lambda{}_\mu T_\nu) - \frac{1}{6} \varepsilon^\lambda{}_{\rho\mu\nu} S^\rho$ .
- The most general class of quadratic Poincaré gauge models that are reduced to General Relativity in the absence of torsion is:

$$S_g = \frac{1}{16\pi} \int \left[ -R + c_2 \tilde{R}_{\lambda\rho\mu\nu} \tilde{R}^{\lambda\mu\rho\nu} - \frac{1}{2} (2c_1 + c_2) \tilde{R}_{\lambda\rho\mu\nu} \tilde{R}^{\mu\nu\lambda\rho} + c_1 \tilde{R}_{\lambda\rho\mu\nu} \tilde{R}^{\lambda\rho\mu\nu} \right. \\ \left. + d_1 \tilde{R}_{\mu\nu} (\tilde{R}^{\mu\nu} - \tilde{R}^{\nu\mu}) + \frac{1}{2} (m_T^2 T_\mu T^\mu + m_S^2 S_\mu S^\mu + m_t^2 t_{\lambda\mu\nu} t^{\lambda\mu\nu}) \right] \sqrt{-g} d^4x.$$

- It is not possible to have a stable propagating torsion tensor in quadratic Poincaré gauge theory for general backgrounds. Kinetic part of vectors  $T_\mu$  and  $S_\mu$  propagate a ghost.

# Cubic Poincaré gauge theory

- Cubic parity preserving branch with mixing terms:<sup>3</sup>

$$\mathcal{L}_{\text{curv-tors}}^{(3)} = \mathcal{L}_{\tilde{R}TT}^{(3)} + \mathcal{L}_{\tilde{R}SS}^{(3)} + \mathcal{L}_{\tilde{R}tt}^{(3)} + \mathcal{L}_{\tilde{R}TS}^{(3)} + \mathcal{L}_{\tilde{R}Tt}^{(3)} + \mathcal{L}_{\tilde{R}St}^{(3)},$$

$$\mathcal{L}_{\tilde{R}TT}^{(3)} = h_1 \tilde{R}_{\mu\nu} T^\mu T^\nu + h_2 \tilde{R} T_\mu T^\mu, \quad \mathcal{L}_{\tilde{R}SS}^{(3)} = h_3 \tilde{R}_{\mu\nu} S^\mu S^\nu + h_4 \tilde{R} S_\mu S^\mu,$$

$$\begin{aligned} \mathcal{L}_{\tilde{R}tt}^{(3)} &= h_5 \tilde{R}_{\lambda\rho\mu\nu} t_\sigma^{\lambda\rho} t^{\sigma\mu\nu} + h_6 \tilde{R}_{\lambda\rho\mu\nu} t_\sigma^{\lambda\mu} t^{\sigma\rho\nu} + h_7 \tilde{R}_{\lambda\rho\mu\nu} t^{\lambda\rho} t^{\sigma\mu\nu} \\ &+ h_8 \tilde{R}_{\lambda\rho\mu\nu} t^{\lambda\mu} t^{\sigma\rho\nu} + h_9 \tilde{R}_{\lambda\rho\mu\nu} t^{\lambda\mu} t^{\rho\nu\sigma} + h_{10} \tilde{R}_{\lambda\rho} t_{\mu\nu}^{\lambda\rho} t^{\rho\mu\nu} \\ &+ h_{11} \tilde{R}_{\lambda\rho} t_{\mu\nu}^{\lambda\rho} t^{\mu\nu\rho} + h_{12} \tilde{R} t_{\lambda\rho} t^{\lambda\rho\mu}, \end{aligned}$$

$$\mathcal{L}_{\tilde{R}TS}^{(3)} = h_{13} \varepsilon^{\lambda\rho\mu\nu} \tilde{R}_{\lambda\rho\mu\nu} T_\sigma S^\sigma + h_{14} \varepsilon_{\nu}^{\lambda\rho\sigma} \tilde{R}_{\lambda\rho\mu\sigma} T^\mu S^\nu + h_{15} \varepsilon^{\lambda\rho\mu\nu} \tilde{R}_{\lambda\rho} T_\mu S_\nu,$$

$$\mathcal{L}_{\tilde{R}Tt}^{(3)} = h_{16} \tilde{R}_{\lambda\rho\mu\nu} T^\nu t^{\lambda\rho\mu} + h_{17} \tilde{R}_{\lambda\rho\mu\nu} T^\rho t^{\lambda\mu\nu} + h_{18} \tilde{R}_{\lambda\rho} T_\mu t^{\mu\lambda\rho} + h_{19} \tilde{R}_{\lambda\rho} T_\mu t^{\lambda\rho\mu},$$

$$\begin{aligned} \mathcal{L}_{\tilde{R}St}^{(3)} &= h_{20} \varepsilon_{\alpha\rho\mu\nu} \tilde{R}_\tau^{\rho\mu\nu} S^\gamma t^{\alpha\tau}_\gamma + h_{21} \varepsilon_{\alpha\rho\mu\nu} \tilde{R}_\tau^{\rho\mu\nu} S^\gamma t_\gamma^{\alpha\tau} \\ &+ h_{22} \varepsilon_{\alpha\rho}^{\mu\nu} \tilde{R}^\rho_{\mu\tau\nu} S^\gamma t_\gamma^{\alpha\tau} + h_{23} \varepsilon_{\alpha\rho}^{\mu\nu} \tilde{R}_{\gamma\mu\tau\nu} S^\alpha t^{\gamma\rho\tau} \\ &+ h_{24} \varepsilon_{\alpha\rho}^{\mu\nu} \tilde{R}_{\gamma\mu\tau\nu} S^\alpha t^{\rho\tau\gamma} + h_{25} \varepsilon_{\alpha\rho\tau\mu} \tilde{R}^\mu_\gamma S^\alpha t^{\rho\tau\gamma} + h_{26} \varepsilon_{\lambda\rho\mu\nu} \tilde{R}^{\lambda\rho} S_\sigma t^{\sigma\mu\nu}. \end{aligned}$$

<sup>3</sup>S. Bahamonde and J. Gigante Valcarcel, Phys. Rev. D **109** (2024) no.10, 10

- First stability constraints (6 equalities):

$$c_2 = 2c_1, \quad h_2 = -\frac{h_1}{2}, \quad h_3 = -\frac{1}{6}(c_1 + 6h_{13}),$$
$$h_4 = \frac{h_{13}}{2}, \quad h_{14} = -2h_{13}, \quad h_{15} = 4h_{13}.$$

- First stability constraints (6 equalities):

$$c_2 = 2c_1, \quad h_2 = -\frac{h_1}{2}, \quad h_3 = -\frac{1}{6}(c_1 + 6h_{13}),$$

$$h_4 = \frac{h_{13}}{2}, \quad h_{14} = -2h_{13}, \quad h_{15} = 4h_{13}.$$

- Second stability constraints (inequalities):

- First stability constraints (6 equalities):

$$c_2 = 2c_1, \quad h_2 = -\frac{h_1}{2}, \quad h_3 = -\frac{1}{6}(c_1 + 6h_{13}),$$
$$h_4 = \frac{h_{13}}{2}, \quad h_{14} = -2h_{13}, \quad h_{15} = 4h_{13}.$$

- Second stability constraints (inequalities):

- Kinetic terms:

$$-\frac{d_1}{6} \leq c_1 \leq -\frac{d_1}{3}, \quad d_1 \leq 0.$$

- First stability constraints (6 equalities):

$$c_2 = 2c_1, \quad h_2 = -\frac{h_1}{2}, \quad h_3 = -\frac{1}{6}(c_1 + 6h_{13}),$$
$$h_4 = \frac{h_{13}}{2}, \quad h_{14} = -2h_{13}, \quad h_{15} = 4h_{13}.$$

- Second stability constraints (inequalities):

- Kinetic terms:

$$-\frac{d_1}{6} \leq c_1 \leq -\frac{d_1}{3}, \quad d_1 \leq 0.$$

- Quartic order of the potential:

$$h_{13} \leq \frac{h_1}{16} \leq (19 + 6\sqrt{10})h_{13}, \quad h_{13} < 0.$$

- First stability constraints (6 equalities):

$$c_2 = 2c_1, \quad h_2 = -\frac{h_1}{2}, \quad h_3 = -\frac{1}{6}(c_1 + 6h_{13}),$$
$$h_4 = \frac{h_{13}}{2}, \quad h_{14} = -2h_{13}, \quad h_{15} = 4h_{13}.$$

- Second stability constraints (inequalities):

- Kinetic terms:

$$-\frac{d_1}{6} \leq c_1 \leq -\frac{d_1}{3}, \quad d_1 \leq 0.$$

- Quartic order of the potential:

$$h_{13} \leq \frac{h_1}{16} \leq (19 + 6\sqrt{10})h_{13}, \quad h_{13} < 0.$$

- Mass terms:

$$m_T^2 \geq 0, \quad m_S^2 \geq 0.$$

# What projects to do for foundations/theory?

- What happens to the tensor sectors of the theory? We set  $t^\lambda{}_{\mu\nu} = 0$ . so we did not demonstrate that the complete torsion is stable under general backgrounds.

# What projects to do for foundations/theory?

- What happens to the tensor sectors of the theory? We set  $t^\lambda{}_{\mu\nu} = 0$ . so we did not demonstrate that the complete torsion is stable under general backgrounds.
- It would be interesting to extend this theory to the parity violating case. This would involve more possible ways to stabilize the theory and new effects.

# What projects to do for foundations/theory?

- What happens to the tensor sectors of the theory? We set  $t^\lambda{}_{\mu\nu} = 0$ . so we did not demonstrate that the complete torsion is stable under general backgrounds.
- It would be interesting to extend this theory to the parity violating case. This would involve more possible ways to stabilize the theory and new effects.
- Mathematics is difficult so we are trying to create a xAct package that can deal with torsional theories in a simpler way.

# What projects to do for foundations/theory?

- What happens to the tensor sectors of the theory? We set  $t^\lambda{}_{\mu\nu} = 0$ . so we did not demonstrate that the complete torsion is stable under general backgrounds.
- It would be interesting to extend this theory to the parity violating case. This would involve more possible ways to stabilize the theory and new effects.
- Mathematics is difficult so we are trying to create a xAct package that can deal with torsional theories in a simpler way.
- Study new interaction between torsion and the electromagnetic field:  $F_{\mu\nu}\tilde{R}^{\mu\nu}$ . What happens to the photon there?

# What projects to do for foundations/theory?

- What happens to the tensor sectors of the theory? We set  $t^\lambda{}_{\mu\nu} = 0$ . so we did not demonstrate that the complete torsion is stable under general backgrounds.
- It would be interesting to extend this theory to the parity violating case. This would involve more possible ways to stabilize the theory and new effects.
- Mathematics is difficult so we are trying to create a xAct package that can deal with torsional theories in a simpler way.
- Study new interaction between torsion and the electromagnetic field:  $F_{\mu\nu}\tilde{R}^{\mu\nu}$ . What happens to the photon there?
- Is it possible to find a renormalizable theory with these cubic interactions?

# Overview of the Talk

- 1 General descriptions of theories with torsion and nonmetricity
- 2 The gauge approach of gravity: Poincare gauge theory
- 3 Fallacies of torsion
- 4 Poincare gauge gravity: Stability and theory
- 5 Black holes**
  - Spherically symmetric black holes
  - Axially symmetric black holes
- 6 Cosmology

# Spherical symmetry

- Explicit symmetries on the metric, torsion and nonmetricity tensors:

$$\mathcal{L}_\xi g_{\mu\nu} = \mathcal{L}_\xi T^\lambda{}_{\mu\nu} = \mathcal{L}_\xi Q_{\lambda\mu\nu} = 0 \implies \mathcal{L}_\xi \tilde{R}^\lambda{}_{\rho\mu\nu} = 0.$$

# Spherical symmetry

- Explicit symmetries on the metric, torsion and nonmetricity tensors:

$$\mathcal{L}_\xi g_{\mu\nu} = \mathcal{L}_\xi T^\lambda{}_{\mu\nu} = \mathcal{L}_\xi Q_{\lambda\mu\nu} = 0 \implies \mathcal{L}_\xi \tilde{R}^\lambda{}_{\rho\mu\nu} = 0.$$

- Static and spherically symmetric space-times:

$$\#10 \rightarrow \#2 \left\{ ds^2 = \Psi_1(r) dt^2 - \frac{dr^2}{\Psi_2(r)} - r^2 (d\vartheta^2 + \sin^2 \vartheta d\varphi^2) ; \right.$$

$$\#24 \rightarrow \#8 \left\{ \begin{array}{ccc} T^t{}_{tr} & T^r{}_{tr} & T^\vartheta{}_{t\vartheta} \\ T^\vartheta{}_{r\vartheta} & T^\vartheta{}_{t\varphi} & T^\vartheta{}_{r\varphi} \\ T^t{}_{\vartheta\varphi} & T^r{}_{\vartheta\varphi} & \end{array} \right.$$

$$\#40 \rightarrow \#12 \left\{ \begin{array}{ccc} Q_{ttt} & Q_{trr} & Q_{ttr} \\ Q_{t\vartheta\vartheta} & Q_{rtt} & Q_{rrr} \\ Q_{rtr} & Q_{r\vartheta\vartheta} & Q_{\vartheta t\vartheta} \\ Q_{\vartheta r\vartheta} & Q_{\vartheta t\varphi} & Q_{\vartheta r\varphi} \end{array} \right.$$

# Reissner-Nordström-like black holes

- Metric and torsion tensors of the solution:

$$T^t{}_{tr} = \frac{\Psi'(r)}{2\Psi(r)} + \frac{wr}{\Psi(r)}, \quad T^r{}_{tr} = T^t{}_{tr}\Psi(r),$$

$$T^\vartheta{}_{t\vartheta} = -T^\vartheta{}_{r\vartheta}\Psi(r), \quad T^\vartheta{}_{r\vartheta} = -\frac{1}{2r} - \frac{wr}{2\Psi(r)},$$

$$T^\vartheta{}_{t\varphi} = -T^\vartheta{}_{r\varphi}\Psi(r), \quad T^\vartheta{}_{r\varphi} = \frac{N_1\kappa_s}{r\Psi(r)}\sin\vartheta,$$

$$T^t{}_{\vartheta\varphi} = \frac{N_2\kappa_s r}{\Psi(r)}\sin\vartheta, \quad T^r{}_{\vartheta\varphi} = T^t{}_{\vartheta\varphi}\Psi(r),$$

$$\Psi_1(r) = \Psi_2(r) = \Psi(r),$$

where  $\Psi(r) = 1 - \frac{2m}{r} + (2N_1 - N_2)(N_1 + N_2) \left[ \frac{2N_1 + N_2}{4N_1 + N_2} d_1 + 2h_{25} \right] \frac{\kappa_s^2}{3r^2}$  and  $w = -\frac{(4N_1 + N_2)(2N_1 + 5N_2)}{6(2N_1 - N_2)[d_1(2N_1 + N_2) + (h_{25} - h_6)(4N_1 + N_2)]} m_t^2$ .

# Reissner-Nordström-like black holes

- Metric and torsion tensors of the solution:

$$T^t{}_{tr} = \frac{\Psi'(r)}{2\Psi(r)} + \frac{wr}{\Psi(r)}, \quad T^r{}_{tr} = T^t{}_{tr}\Psi(r),$$

$$T^\vartheta{}_{t\vartheta} = -T^\vartheta{}_{r\vartheta}\Psi(r), \quad T^\vartheta{}_{r\vartheta} = -\frac{1}{2r} - \frac{wr}{2\Psi(r)},$$

$$T^\vartheta{}_{t\varphi} = -T^\vartheta{}_{r\varphi}\Psi(r), \quad T^\vartheta{}_{r\varphi} = \frac{N_1\kappa_s}{r\Psi(r)}\sin\vartheta,$$

$$T^t{}_{\vartheta\varphi} = \frac{N_2\kappa_s r}{\Psi(r)}\sin\vartheta, \quad T^r{}_{\vartheta\varphi} = T^t{}_{\vartheta\varphi}\Psi(r),$$

$$\Psi_1(r) = \Psi_2(r) = \Psi(r),$$

where  $\Psi(r) = 1 - \frac{2m}{r} + (2N_1 - N_2)(N_1 + N_2) \left[ \frac{2N_1 + N_2}{4N_1 + N_2} d_1 + 2h_{25} \right] \frac{\kappa_s^2}{3r^2}$  and  
 $w = -\frac{(4N_1 + N_2)(2N_1 + 5N_2)}{6(2N_1 - N_2)[d_1(2N_1 + N_2) + (h_{25} - h_6)(4N_1 + N_2)]} m_t^2$ .

- Reduced vector and axial sectors:

$$\mathcal{L}_g = \frac{1}{16\pi} \left[ -R + \frac{2}{9} (3c_1 + d_1) F_{\mu\nu}^{(T)} F^{(T)\mu\nu} - \frac{1}{72} (6c_1 + d_1) F_{\mu\nu}^{(S)} F^{(S)\mu\nu} \right].$$

# Electrodynamics coupled with torsion

- the most general extension theory that is parity-preserving and satisfies that the extended Lagrangian is linear in curvature  $\tilde{R}^\lambda_{\rho\mu\nu}$  and in the field strength  $F_{\mu\nu}$ , and quadratic in torsion  $T^\lambda_{\mu\nu}$ , is:

$$\mathcal{L} = -R - 4k_1 F_{\mu\nu} F^{\mu\nu} + k_2 \tilde{R}^2 + k_3 F^{\mu\nu} \tilde{R}_{\mu\nu} + k_4 F^{\mu\nu} T_\mu^{\alpha\lambda} T_{\alpha\nu\lambda} + k_5 F^{\mu\nu} T_{\mu\nu}^\alpha T_\alpha + k_6 F^{\mu\nu} T^\alpha_{\mu\nu}$$

# Electrodynamics coupled with torsion

- the most general extension theory that is parity-preserving and satisfies that the extended Lagrangian is linear in curvature  $\tilde{R}^\lambda_{\rho\mu\nu}$  and in the field strength  $F_{\mu\nu}$ , and quadratic in torsion  $T^\lambda_{\mu\nu}$ , is:

$$\mathcal{L} = -R - 4k_1 F_{\mu\nu} F^{\mu\nu} + k_2 \tilde{R}^2 + k_3 F^{\mu\nu} \tilde{R}_{\mu\nu} + k_4 F^{\mu\nu} T_\mu^{\alpha\lambda} T_{\alpha\nu\lambda} + k_5 F^{\mu\nu} T_{\mu\nu}^\alpha T_\alpha + k_6 F^{\mu\nu} T^\alpha_{\mu\nu}$$

- We found the following black hole solution:

$$t_1(r) = \frac{\Psi'(r)}{2\Psi(r)} + \frac{c_1}{\Psi(r)} + \frac{\kappa_s}{r\Psi(r)}, \quad t_2(r) = \Psi(r) \left( t_1(r) - t_4(r) - \frac{2}{r} \right), \quad (1)$$

$$t_3(r) = \frac{\Psi(r)(1 + rt_4(r))}{r}, \quad t_5(r) = t_6(r) = t_7(r) = t_8(r) = 0, \quad t_4(r) = -\frac{1}{r}.$$

With the following metric and electric potential

$$\Psi(r) = 1 - \frac{2m}{r} + \frac{k_1 q^2}{r^2} - \frac{k_3 \kappa_s q}{4r^2} - \frac{k_3^2 q^2}{128k_2 r^2},$$

$$A_\mu = \left( \frac{q}{r}, 0, 0, 0 \right).$$

# Electrodynamics coupled with torsion

- the most general extension theory that is parity-preserving and satisfies that the extended Lagrangian is linear in curvature  $\tilde{R}^\lambda_{\rho\mu\nu}$  and in the field strength  $F_{\mu\nu}$ , and quadratic in torsion  $T^\lambda_{\mu\nu}$ , is:

$$\mathcal{L} = -R - 4k_1 F_{\mu\nu} F^{\mu\nu} + k_2 \tilde{R}^2 + k_3 F^{\mu\nu} \tilde{R}_{\mu\nu} + k_4 F^{\mu\nu} T_\mu^{\alpha\lambda} T_{\alpha\nu\lambda} + k_5 F^{\mu\nu} T_{\mu\nu}^\alpha T_\alpha + k_6 F^{\mu\nu} T^\alpha_{\mu\nu}$$

- We found the following black hole solution:

$$t_1(r) = \frac{\Psi'(r)}{2\Psi(r)} + \frac{c_1}{\Psi(r)} + \frac{\kappa_s}{r\Psi(r)}, \quad t_2(r) = \Psi(r) \left( t_1(r) - t_4(r) - \frac{2}{r} \right), \quad (1)$$

$$t_3(r) = \frac{\Psi(r)(1 + rt_4(r))}{r}, \quad t_5(r) = t_6(r) = t_7(r) = t_8(r) = 0, \quad t_4(r) = -\frac{1}{r}.$$

With the following metric and electric potential

$$\Psi(r) = 1 - \frac{2m}{r} + \frac{k_1 q^2}{r^2} - \frac{k_3 \kappa_s q}{4r^2} - \frac{k_3^2 q^2}{128 k_2 r^2},$$

$$A_\mu = \left( \frac{q}{r}, 0, 0, 0 \right).$$

- New coupling between spin charge  $\kappa_s$  and electric charge  $q$ .

# Electrodynamics coupled with torsion

- the most general extension theory that is parity-preserving and satisfies that the extended Lagrangian is linear in curvature  $\tilde{R}^\lambda_{\rho\mu\nu}$  and in the field strength  $F_{\mu\nu}$ , and quadratic in torsion  $T^\lambda_{\mu\nu}$ , is:

$$\mathcal{L} = -R - 4k_1 F_{\mu\nu} F^{\mu\nu} + k_2 \tilde{R}^2 + k_3 F^{\mu\nu} \tilde{R}_{\mu\nu} + k_4 F^{\mu\nu} T_\mu^{\alpha\lambda} T_{\alpha\nu\lambda} + k_5 F^{\mu\nu} T_{\mu\nu}^\alpha T_\alpha + k_6 F^{\mu\nu} T^\alpha_{\mu\nu}$$

- We found the following black hole solution:

$$t_1(r) = \frac{\Psi'(r)}{2\Psi(r)} + \frac{c_1}{\Psi(r)} + \frac{\kappa_s}{r\Psi(r)}, \quad t_2(r) = \Psi(r) \left( t_1(r) - t_4(r) - \frac{2}{r} \right), \quad (1)$$

$$t_3(r) = \frac{\Psi(r)(1 + rt_4(r))}{r}, \quad t_5(r) = t_6(r) = t_7(r) = t_8(r) = 0, \quad t_4(r) = -\frac{1}{r}.$$

With the following metric and electric potential

$$\Psi(r) = 1 - \frac{2m}{r} + \frac{k_1 q^2}{r^2} - \frac{k_3 \kappa_s q}{4r^2} - \frac{k_3^2 q^2}{128 k_2 r^2},$$

$$A_\mu = \left( \frac{q}{r}, 0, 0, 0 \right).$$

- New coupling between spin charge  $\kappa_s$  and electric charge  $q$ .
- Different charges would give rise to different phenomenology.

# What does this charge represent?

- 1 Intrinsic spin generates gravitation. This effect does not exist in GR.

# What does this charge represent?

- 1 Intrinsic spin generates gravitation. This effect does not exist in GR.
- 2 We know that the spin is a fundamental property of particles. Since their masses contribute to gravity, why their spin do not?

# What does this charge represent?

- 1 Intrinsic spin generates gravitation. This effect does not exist in GR.
- 2 We know that the spin is a fundamental property of particles. Since their masses contribute to gravity, why their spin do not?
- 3 The solution is in vacuum and a charge  $\kappa_s$  appears (spin charge). Analogue to the case of Schwarzschild where the mass  $M$  appears.

# What does this charge represent?

- 1 Intrinsic spin generates gravitation. This effect does not exist in GR.
- 2 We know that the spin is a fundamental property of particles. Since their masses contribute to gravity, why their spin do not?
- 3 The solution is in vacuum and a charge  $\kappa_s$  appears (spin charge). Analogue to the case of Schwarzschild where the mass  $M$  appears.
- 4 We expect that the spin charge might be important in certain astrophysical scenarios such as: highly magnetized neutron stars; supermassive black holes with endowed spin.

# Axially symmetric black holes

- We are now working on the slowly rotating case. This problem involves the full axially symmetric torsion containing 24 dof and 4 dof of the metric.

# Axially symmetric black holes

- We are now working on the slowly rotating case. This problem involves the full axially symmetric torsion containing 24 dof and 4 dof of the metric.
- It is an extremely difficult problem to solve the system. One can separate it into non-dynamical ( $\kappa_s = 0$ ) and dynamical part  $\kappa_s \neq 0$ .

# Axially symmetric black holes

- We are now working on the slowly rotating case. This problem involves the full axially symmetric torsion containing 24 dof and 4 dof of the metric.
- It is an extremely difficult problem to solve the system. One can separate it into non-dynamical ( $\kappa_s = 0$ ) and dynamical part  $\kappa_s \neq 0$ .
- We recently found a solution in the non-dynamical part and with that part, we are investigating the dynamical part.

# Axially symmetric black holes

- We are now working on the slowly rotating case. This problem involves the full axially symmetric torsion containing 24 dof and 4 dof of the metric.
- It is an extremely difficult problem to solve the system. One can separate it into non-dynamical ( $\kappa_s = 0$ ) and dynamical part  $\kappa_s \neq 0$ .
- We recently found a solution in the non-dynamical part and with that part, we are investigating the dynamical part.
- In spherical symmetry we obtained RN, but in axial symmetry we expect to have an extension of Kerr-Newman with new interactions between  $\kappa_s$  (intrinsic spin) and macroscopic spin  $a$ .

## Spin-Orbit Interaction in Atomic Physics

The spin-orbit interaction is a fundamental quantum mechanical effect that describes how an electron's intrinsic spin interacts with its orbital motion around the nucleus. This interaction leads to energy level splitting in atoms, particularly noticeable in heavy elements.

## Spin-Orbit Interaction in Atomic Physics

The spin-orbit interaction is a fundamental quantum mechanical effect that describes how an electron's intrinsic spin interacts with its orbital motion around the nucleus. This interaction leads to energy level splitting in atoms, particularly noticeable in heavy elements.

- This interaction is of the following form

$$\mathcal{L}_{SO} = \frac{\mu}{4m^2} \bar{\psi} \sigma^{\mu\nu} F_{\mu\nu} \psi$$

## Spin-Orbit Interaction in Atomic Physics

The spin-orbit interaction is a fundamental quantum mechanical effect that describes how an electron's intrinsic spin interacts with its orbital motion around the nucleus. This interaction leads to energy level splitting in atoms, particularly noticeable in heavy elements.

- This interaction is of the following form

$$\mathcal{L}_{SO} = \frac{\mu}{4m^2} \bar{\psi} \sigma^{\mu\nu} F_{\mu\nu} \psi$$

- Then,

$$\mathcal{L}_{SO} = \lambda(r) \mathbf{L} \cdot \mathbf{S}$$

where  $\mathbf{L}$  is the orbital angular momentum,  $\mathbf{S}$  is the spin angular momentum, and  $\lambda(r)$  is a coupling function.

## Spin-Orbit Interaction in Atomic Physics

The spin-orbit interaction is a fundamental quantum mechanical effect that describes how an electron's intrinsic spin interacts with its orbital motion around the nucleus. This interaction leads to energy level splitting in atoms, particularly noticeable in heavy elements.

- This interaction is of the following form

$$\mathcal{L}_{SO} = \frac{\mu}{4m^2} \bar{\psi} \sigma^{\mu\nu} F_{\mu\nu} \psi$$

- Then,

$$\mathcal{L}_{SO} = \lambda(r) \mathbf{L} \cdot \mathbf{S}$$

where  $\mathbf{L}$  is the orbital angular momentum,  $\mathbf{S}$  is the spin angular momentum, and  $\lambda(r)$  is a coupling function.

- The spin-orbit interaction increases the energy gap between certain nuclear energy levels, making nuclei with magic numbers more stable.

# Axially symmetric black holes - spin orbit interaction

- Our main aim is to find out if a similar effect would appear in gravity: gravitational spin-orbit interaction.

# Axially symmetric black holes - spin orbit interaction

- Our main aim is to find out if a similar effect would appear in gravity: gravitational spin-orbit interaction.
- In this case, this would be an interaction between the angular momentum  $a$  and the intrinsic spin  $\kappa_s$ .

# Axially symmetric black holes - spin orbit interaction

- Our main aim is to find out if a similar effect would appear in gravity: gravitational spin-orbit interaction.
- In this case, this would be an interaction between the angular momentum  $a$  and the intrinsic spin  $\kappa_s$ .
- In axial symmetry, the Lagrangian of our theory can be written as

$$\mathcal{L}_{\text{SO}} = \frac{1}{2\kappa^2 r^4} \left( d_1 F_1(r, \theta) + h_{17} F_2(r, \theta) \right) a \kappa_s \cos \vartheta$$

# Axially symmetric black holes - spin orbit interaction

- Our main aim is to find out if a similar effect would appear in gravity: gravitational spin-orbit interaction.
- In this case, this would be an interaction between the angular momentum  $a$  and the intrinsic spin  $\kappa_s$ .
- In axial symmetry, the Lagrangian of our theory can be written as

$$\mathcal{L}_{\text{SO}} = \frac{1}{2\kappa^2 r^4} \left( d_1 F_1(r, \theta) + h_{17} F_2(r, \theta) \right) a \kappa_s \cos \vartheta$$

- So, it has the same form as the spin-orbit interaction!

# Axially symmetric black holes - spin orbit interaction

- Our main aim is to find out if a similar effect would appear in gravity: gravitational spin-orbit interaction.
- In this case, this would be an interaction between the angular momentum  $a$  and the intrinsic spin  $\kappa_s$ .
- In axial symmetry, the Lagrangian of our theory can be written as

$$\mathcal{L}_{\text{SO}} = \frac{1}{2\kappa^2 r^4} \left( d_1 F_1(r, \theta) + h_{17} F_2(r, \theta) \right) a \kappa_s \cos \vartheta$$

- So, it has the same form as the spin-orbit interaction!
- $F_1, F_2$  depend on the non-dynamical part of the problem. We were able to solve this part but so far, we only found situations where  $F_1 = 0$  and  $h_{17} = 0$ .

# Axially symmetric black holes - spin orbit interaction

- Our main aim is to find out if a similar effect would appear in gravity: gravitational spin-orbit interaction.
- In this case, this would be an interaction between the angular momentum  $a$  and the intrinsic spin  $\kappa_s$ .
- In axial symmetry, the Lagrangian of our theory can be written as

$$\mathcal{L}_{\text{SO}} = \frac{1}{2\kappa^2 r^4} \left( d_1 F_1(r, \theta) + h_{17} F_2(r, \theta) \right) a \kappa_s \cos \vartheta$$

- So, it has the same form as the spin-orbit interaction!
- $F_1, F_2$  depend on the non-dynamical part of the problem. We were able to solve this part but so far, we only found situations where  $F_1 = 0$  and  $h_{17} = 0$ .
- The system allows to have many non-dynamical solutions and it seems that we have not found the correct branch where  $\mathcal{L}_{\text{SO}} \neq 0$ .

# Axially symmetric black holes - spin orbit interaction

- Our main aim is to find out if a similar effect would appear in gravity: gravitational spin-orbit interaction.
- In this case, this would be an interaction between the angular momentum  $a$  and the intrinsic spin  $\kappa_s$ .
- In axial symmetry, the Lagrangian of our theory can be written as

$$\mathcal{L}_{\text{SO}} = \frac{1}{2\kappa^2 r^4} \left( d_1 F_1(r, \theta) + h_{17} F_2(r, \theta) \right) a \kappa_s \cos \vartheta$$

- So, it has the same form as the spin-orbit interaction!
- $F_1, F_2$  depend on the non-dynamical part of the problem. We were able to solve this part but so far, we only found situations where  $F_1 = 0$  and  $h_{17} = 0$ .
- The system allows to have many non-dynamical solutions and it seems that we have not found the correct branch where  $\mathcal{L}_{\text{SO}} \neq 0$ .
- Another possibility is that in gravity, the gravitational spin-orbit interaction would not be of the form  $a \kappa_s$  but  $a^2 \kappa_s$  or  $a \kappa_s^2$ .

# What projects to do for Black Holes?

- Extend the spherically symmetric black hole solution including parity violating terms.

# What projects to do for Black Holes?

- Extend the spherically symmetric black hole solution including parity violating terms.
- Study the Gauss-Bonnet invariant with torsion/nonmetricity and couple it with a scalar field. This arena can have a good potential avenue.

# What projects to do for Black Holes?

- Extend the spherically symmetric black hole solution including parity violating terms.
- Study the Gauss-Bonnet invariant with torsion/nonmetricity and couple it with a scalar field. This arena can have a good potential avenue.
- Study the quasinormal modes of the spherically symmetric solution. Is it stable under spherically symmetric perturbations?

# What projects to do for Black Holes?

- Extend the spherically symmetric black hole solution including parity violating terms.
- Study the Gauss-Bonnet invariant with torsion/nonmetricity and couple it with a scalar field. This arena can have a good potential avenue.
- Study the quasinormal modes of the spherically symmetric solution. Is it stable under spherically symmetric perturbations?
- Solve the full system in the slowly rotating case and find out if the metric is different to Kerr-Newman.

# What projects to do for Black Holes?

- Extend the spherically symmetric black hole solution including parity violating terms.
- Study the Gauss-Bonnet invariant with torsion/nonmetricity and couple it with a scalar field. This arena can have a good potential avenue.
- Study the quasinormal modes of the spherically symmetric solution. Is it stable under spherically symmetric perturbations?
- Solve the full system in the slowly rotating case and find out if the metric is different to Kerr-Newman.
- If we are able to do so, we would be able to find a new effect in gravity: Grav. spin orbit interaction. Is it possible to measure this?

# What projects to do for Black Holes?

- Extend the spherically symmetric black hole solution including parity violating terms.
- Study the Gauss-Bonnet invariant with torsion/nonmetricity and couple it with a scalar field. This arena can have a good potential avenue.
- Study the quasinormal modes of the spherically symmetric solution. Is it stable under spherically symmetric perturbations?
- Solve the full system in the slowly rotating case and find out if the metric is different to Kerr-Newman.
- If we are able to do so, we would be able to find a new effect in gravity: Grav. spin orbit interaction. Is it possible to measure this?
- Study neutron stars and study the effect of the intrinsic spin in such scenarios.

# Overview of the Talk

- 1 General descriptions of theories with torsion and nonmetricity
- 2 The gauge approach of gravity: Poincare gauge theory
- 3 Fallacies of torsion
- 4 Poincare gauge gravity: Stability and theory
- 5 Black holes
  - Spherically symmetric black holes
  - Axially symmetric black holes
- 6 **Cosmology**

# Brief discussion on cosmology

- Any realistic theory should describe both background and cosmological perturbations observables (for example CMB, dark energy, large scale structure, etc.)

# Brief discussion on cosmology

- Any realistic theory should describe both background and cosmological perturbations observables (for example CMB, dark energy, large scale structure, etc.)
- So far, the majority of the studies in MAG have been concentrated on describing background cosmology only. A few models (very specific) goes beyond background.

# Brief discussion on cosmology

- Any realistic theory should describe both background and cosmological perturbations observables (for example CMB, dark energy, large scale structure, etc.)
- So far, the majority of the studies in MAG have been concentrated on describing background cosmology only. A few models (very specific) goes beyond background.
- The majority of these studies predominantly focus on torsion.

# Brief discussion on cosmology

- Any realistic theory should describe both background and cosmological perturbations observables (for example CMB, dark energy, large scale structure, etc.)
- So far, the majority of the studies in MAG have been concentrated on describing background cosmology only. A few models (very specific) goes beyond background.
- The majority of these studies predominantly focus on torsion.
- Usually, it is possible to avoid cosmological singularities and replace them a cosmic bounce.

# Brief discussion on cosmology

- Any realistic theory should describe both background and cosmological perturbations observables (for example CMB, dark energy, large scale structure, etc.)
- So far, the majority of the studies in MAG have been concentrated on describing background cosmology only. A few models (very specific) goes beyond background.
- The majority of these studies predominantly focus on torsion.
- Usually, it is possible to avoid cosmological singularities and replace them a cosmic bounce.
- Dark energy can be explained by the scalar modes of torsion.

# Brief discussion on cosmology

- Any realistic theory should describe both background and cosmological perturbations observables (for example CMB, dark energy, large scale structure, etc.)
- So far, the majority of the studies in MAG have been concentrated on describing background cosmology only. A few models (very specific) goes beyond background.
- The majority of these studies predominantly focus on torsion.
- Usually, it is possible to avoid cosmological singularities and replace them a cosmic bounce.
- Dark energy can be explained by the scalar modes of torsion.
- It is possible to find inflationary models such as Einstein-Cartan couple to Higgs or other more complicated ones which are compatible with observations.

- Let us assume that the metric, torsion and nonmetricity have the same cosmological symmetries (isotropy and homogeneity)

$$\mathcal{L}_\xi \bar{g}_{\mu\nu} = \mathcal{L}_\xi \bar{T}^\lambda{}_{\mu\nu} = \mathcal{L}_\xi \bar{Q}^\lambda{}_{\mu\nu} = 0.$$

- Let us assume that the metric, torsion and nonmetricity have the same cosmological symmetries (isotropy and homogeneity)

$$\mathcal{L}_\xi \bar{g}_{\mu\nu} = \mathcal{L}_\xi \bar{T}^\lambda{}_{\mu\nu} = \mathcal{L}_\xi \bar{Q}^\lambda{}_{\mu\nu} = 0.$$

- By solving those equations one get the FLRW metric and torsion+nonmetricity satisfying homogeneity and isotropy:

$$\begin{aligned}\bar{g} &= -\bar{n}_\mu \bar{n}_\nu dx^\mu \otimes dx^\nu + \bar{P}_{\mu\nu} dx^\mu \otimes dx^\nu = -N^2 dt \otimes dt + a^2 \gamma_{ij} dx^i \otimes dx^j, \\ \bar{T}^\lambda{}_{\mu\nu} &= 2T_1(t) \bar{n}_{[\mu} \bar{P}_{\nu]}{}^\lambda + 2T_2(t) \bar{\varepsilon}^\lambda{}_{\mu\nu\rho} \bar{n}^\rho, \\ \bar{Q}^\lambda{}_{\mu\nu} &= 2Q_1(t) \bar{n}_\lambda \bar{n}_\mu \bar{n}_\nu + 2Q_2(t) \bar{n}_\lambda \bar{P}_{\mu\nu} + 2Q_3(t) \bar{P}_{\lambda(\mu} \bar{n}_{\nu)},\end{aligned}$$

where  $\gamma_{ij} dx^i \otimes dx^j = \frac{dr^2}{1-Kr^2} + r^2 d\Omega^2$ . Note that there are 5 independent functions coming from Post-Riemannian.

# Cosmology in MAG - matter

- One can consider that the energy-momentum tensor is described by a standard perfect fluid described by

$$T_{\mu\nu} = (\rho(t) + p(t)) n_{\mu}n_{\nu} + p(t)g_{\mu\nu} = \rho(t)n_{\mu}n_{\nu} + p(t)p_{\mu\nu} ,$$

# Cosmology in MAG - matter

- One can consider that the energy-momentum tensor is described by a standard perfect fluid described by

$$T_{\mu\nu} = (\rho(t) + p(t)) n_\mu n_\nu + p(t) g_{\mu\nu} = \rho(t) n_\mu n_\nu + p(t) p_{\mu\nu} ,$$

- Considering matter described by an unconstrained hyperfluid respecting the Copernican Principle and also respecting the cosmological principle (isotropy and homogeneity), we find that the hypermomentum is

$$\Delta_{\lambda\mu\nu} = \frac{1}{3} \Delta_1(t) p_{\lambda\mu} n_\nu + \Delta_2(t) p_{\lambda\nu} n_\mu + \Delta_3(t) n_\lambda p_{\mu\nu} + \frac{1}{4} \Delta_4(t) n_\lambda n_\mu n_\nu + \Delta_5(t) \varepsilon_{\lambda\mu\nu\rho} n^\rho$$

which contains 5 different sources dof related to the intrinsic spin, dilations, and shears.

# Cosmology in MAG - matter

- One can consider that the energy-momentum tensor is described by a standard perfect fluid described by

$$T_{\mu\nu} = (\rho(t) + p(t)) n_\mu n_\nu + p(t) g_{\mu\nu} = \rho(t) n_\mu n_\nu + p(t) p_{\mu\nu} ,$$

- Considering matter described by an unconstrained hyperfluid respecting the Copernican Principle and also respecting the cosmological principle (isotropy and homogeneity), we find that the hypermomentum is

$$\Delta_{\lambda\mu\nu} = \frac{1}{3} \Delta_1(t) p_{\lambda\mu} n_\nu + \Delta_2(t) p_{\lambda\nu} n_\mu + \Delta_3(t) n_\lambda p_{\mu\nu} + \frac{1}{4} \Delta_4(t) n_\lambda n_\mu n_\nu + \Delta_5(t) \varepsilon_{\lambda\mu\nu\rho} n^\rho$$

which contains 5 different sources dof related to the intrinsic spin, dilations, and shears.

- For Cubic Poincare we found the following energy-conservation:

$$\dot{\rho} + 3H(\rho + p) = 3^{(s)} \Delta_5 \left( HT_2 + \dot{T}_2 \right) - 3^{(s)} \Delta_3 \left( \dot{H} - HT_1 + H^2 - \dot{T}_1 \right) .$$

# SVT decomposition around FRW

- The 10 dof described by the metric perturbations are split in terms of four scalars  $\{\alpha, \beta, \zeta, h\}$  (1 dof each), two transverse vectors  $\{\beta_i^{(T)}, h_i^{(T)}\}$  (2 dof each), and one symmetric and transverse-traceless tensor  $h_{ij}^{(TT)}$  (2 dof).

# SVT decomposition around FRW

- The 10 dof described by the metric perturbations are split in terms of four scalars  $\{\alpha, \beta, \zeta, h\}$  (1 dof each), two transverse vectors  $\{\beta_i^{(T)}, h_i^{(T)}\}$  (2 dof each), and one symmetric and transverse-traceless tensor  $h_{ij}^{(TT)}$  (2 dof).

SVT	Quantities	dof	Total dof
5 scalars	$\{T, B, \phi, A, \varrho\}$	1 dof each	5
3 pseudoscalars	$\{\mathcal{S}, \mathcal{B}, \mathcal{A}\}$	1 dof each	3
3 vectors	$\{T_i^{(T)}, B_i^{(T)}, A_i^{(T)}\}$	2 dof each	6
3 pseudovectors	$\{\mathcal{S}_i^{(T)}, \mathcal{B}_i^{(T)}, \mathcal{A}_i^{(T)}\}$	2 dof each	6
1 rank-2 tensor	$\{A_{ij}^{(TT)}\}$	2 dof each	2
1 rank-2 pseudotensor	$\{\mathcal{A}_{ij}^{(TT)}\}$	2 dof each	2

**Table:** Perturbation spectrum for the torsion tensor. K. Aoki, S. Bahamonde, J. Gigante Valcarcel and M. A. Gorji, "Cosmological Perturbation Theory in Metric-Affine Gravity," Phys. Rev. D **110** (2024) no.2, 2.

# SVT decomposition around FRW

SVT	Quantities	dof	Total dof
10 scalars	$\{\theta, \psi, \xi, \Lambda, Y, Z, \kappa, Q, W, C\}$	1 dof each	10
2 pseudoscalars	$\{\mathcal{Y}, \mathcal{Q}\}$	1 dof each	2
7 vectors	$\{\Lambda^{(T)}_i, Y^{(T)}_i, Z^{(T)}_i, \kappa^{(T)}_i, Q^{(T)}_i, W^{(T)}_i, C^{(T)}_i\}$	2 dof each	14
2 pseudovectors	$\{\mathcal{Y}^{(T)}_i, \mathcal{Q}^{(T)}_i\}$	2 dof each	4
3 rank-2 tensor	$\{\kappa^{(TT)}_{ij}, Q^{(TT)}_{ij}, C^{(TT)}_{ij}\}$	2 dof each	6
1 rank-2 pseudotensor	$\{\mathcal{Q}^{(TT)}_{ij}\}$	2 dof each	2
1 rank-3 tensor	$\{C^{(TT)}_{ijk}\}$	2 dof each	2

**Table:** Perturbation spectrum for the nonmetricity tensor.

# SVT decomposition around FRW

SVT	Quantities	dof	Total dof
10 scalars	$\{\theta, \psi, \xi, \Lambda, Y, Z, \kappa, Q, W, C\}$	1 dof each	10
2 pseudoscalars	$\{\mathcal{Y}, \mathcal{Q}\}$	1 dof each	2
7 vectors	$\{\Lambda^{(T)}_i, Y^{(T)}_i, Z^{(T)}_i, \kappa^{(T)}_i, Q^{(T)}_i, W^{(T)}_i, C^{(T)}_i\}$	2 dof each	14
2 pseudovectors	$\{\mathcal{Y}^{(T)}_i, \mathcal{Q}^{(T)}_i\}$	2 dof each	4
3 rank-2 tensor	$\{\kappa^{(TT)}_{ij}, Q^{(TT)}_{ij}, C^{(TT)}_{ij}\}$	2 dof each	6
1 rank-2 pseudotensor	$\{\mathcal{Q}^{(TT)}_{ij}\}$	2 dof each	2
1 rank-3 tensor	$\{C^{(TT)}_{ijk}\}$	2 dof each	2

**Table:** Perturbation spectrum for the nonmetricity tensor.

- Note that the spin-3 carries a helicity-3 part and since the metric does not have such terms, it totally decouples from the other modes in FLRW.

# SVT decomposition around FRW

SVT	Quantities	dof	Total dof
10 scalars	$\{\theta, \psi, \xi, \Lambda, Y, Z, \kappa, Q, W, C\}$	1 dof each	10
2 pseudoscalars	$\{\mathcal{Y}, \mathcal{Q}\}$	1 dof each	2
7 vectors	$\{\Lambda^{(T)}_i, Y^{(T)}_i, Z^{(T)}_i, \kappa^{(T)}_i, Q^{(T)}_i, W^{(T)}_i, C^{(T)}_i\}$	2 dof each	14
2 pseudovectors	$\{\mathcal{Y}^{(T)}_i, \mathcal{Q}^{(T)}_i\}$	2 dof each	4
3 rank-2 tensor	$\{\kappa^{(TT)}_{ij}, Q^{(TT)}_{ij}, C^{(TT)}_{ij}\}$	2 dof each	6
1 rank-2 pseudotensor	$\{\mathcal{Q}^{(TT)}_{ij}\}$	2 dof each	2
1 rank-3 tensor	$\{C^{(TT)}_{ijk}\}$	2 dof each	2

**Table:** Perturbation spectrum for the nonmetricity tensor.

- Note that the spin-3 carries a helicity-3 part and since the metric does not have such terms, it totally decouples from the other modes in FLRW.
- We studied this spin-3 in quadratic MAG finding

$$\ddot{C}^{(A)} + 3H\dot{C}^{(A)} + [\omega_{C,k}^{(A)}]^2 C^{(A)} = J^{(A)}.$$

# What projects to do for Cosmology?

- Can torsion/nonmetricity in any of these theories might help to alleviate tensions in cosmology?

# What projects to do for Cosmology?

- Can torsion/nonmetricity in any of these theories might help to alleviate tensions in cosmology?
- We know very well that  $p = p(\rho)$  and how to associate that to an EoS (radiation,dust...). However, how are hypermomentum functions  $\Delta_i$  associated to  $\rho$ ? This is related to statistical mechanical properties of the fluid with micro-structure.

# What projects to do for Cosmology?

- Can torsion/nonmetricity in any of these theories might help to alleviate tensions in cosmology?
- We know very well that  $p = p(\rho)$  and how to associate that to an EoS (radiation,dust...). However, how are hypermomentum functions  $\Delta_i$  associated to  $\rho$ ? This is related to statistical mechanical properties of the fluid with micro-structure.
- Perform the cosmological perturbations of the cubic Poincare theory in order to find if the tensor part is stable. Study new interactions between the spin-2 part of torsion and the graviton in cosmology?

# What projects to do for Cosmology?

- Can torsion/nonmetricity in any of these theories might help to alleviate tensions in cosmology?
- We know very well that  $p = p(\rho)$  and how to associate that to an EoS (radiation,dust...). However, how are hypermomentum functions  $\Delta_i$  associated to  $\rho$ ? This is related to statistical mechanical properties of the fluid with micro-structure.
- Perform the cosmological perturbations of the cubic Poincare theory in order to find if the tensor part is stable. Study new interactions between the spin-2 part of torsion and the graviton in cosmology?
- Cosmic birefringence naturally appears in theories with torsion/nonmetricity. Can one explain this effect in a simple theory instead of the standard axion theory  $\tilde{F}^{\mu\nu} F_{\mu\nu} \phi$ ?

# What projects to do for Cosmology?

- Can torsion/nonmetricity in any of these theories might help to alleviate tensions in cosmology?
- We know very well that  $p = p(\rho)$  and how to associate that to an EoS (radiation,dust...). However, how are hypermomentum functions  $\Delta_i$  associated to  $\rho$ ? This is related to statistical mechanical properties of the fluid with micro-structure.
- Perform the cosmological perturbations of the cubic Poincare theory in order to find if the tensor part is stable. Study new interactions between the spin-2 part of torsion and the graviton in cosmology?
- Cosmic birefringence naturally appears in theories with torsion/nonmetricity. Can one explain this effect in a simple theory instead of the standard axion theory  $\tilde{F}^{\mu\nu} F_{\mu\nu} \phi$ ?
- The massive spin-3 part of nonmetricity might be a good candidate for dark matter. This has not been addressed in detail.

# Thank You for Listening!

*Questions? Comments?*

---

**Join us to work in all of these questions!**